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**AMRL-TR-77-62** 



# THE SAINT USER'S MANUAL

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**JUNE 1978** 

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FOR THE COMMANDER

CIMPLES BATES, JR.

Chief

**Human Engineering Division** 

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SECURITY CLASSIFICATION OF THIS PAGE (When Date Entered) **READ INSTRUCTIONS** REPORT DOCUMENTATION PAGE BEFORE COMPLETING FORM 2. GOVT ACCESSION NO. 3. RECIPIENT'S CATALOG NUMBER AMRL TR-77-62 TITLE (and Subtitle) TERIOD COVERED THE SAINT USER'S MANUAL 75-Dec NG ORG. REPORT NUMBER CONTRACT OR GRANT NUMBER(A) Deborah J. /Seifert\* David B./Wortman\* Gerald P./Chubb\*\* Steven D. Duket\*. F33615-76-C-5012 9. PERFORMING ORGANIZATION NAME AND ADDRESS PROGRAM ELEMENT, PROJECT, TASK AREA & WORK LINIT NUMBERS Pritsker & Associates\* Aerospace Med. 62282F; 7184/13-03 P.O. Box 2413 Research Lab. \*\* West Lafayette, IN 47906 WPAFB, OH 45433 11. CONTROLLING OFFICE NAME AND ADDRESS Aerospace Medical Research Laboratory Jun 6 78 Aerospace Medical Division, AFSC Wright-Patterson Air Force Base, OH 45433 142 14. MONITORING AGENCY NAME & ADDRESS(II different from Controlling Office) 15. SECURITY CLASS. (of this re Unclassified 15. DECLASSIFICATION DOWNGRADING SCHEDULE 16. DISTRIBUTION STATEMENT (of this Report) Approved for public release; distribution unlimited 17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, If different from Report) 18. SUPPLEMENTARY NOTES 19 KEY WORDS (Continue on reverse side II necessary and identify by block number) Computers; Modeling; Operator Loading; Operations Research; Mission Analysis; Survivability/Vulnerability; Man-Machine Systems; Crew Performance; Networks; Simulation; Discrete Event Simulation; Next Event Simulation; Continuous Simulation; Combined Simulation; Simulation Languages; SAINT ABSTRACT (Continue on reverse side if necessary and identify by block number) he procedures for using the SAINT simulation program to analyze system models are described in detail. SAINT (Systems Analysis of Integrated Networks of Tasks) is a network modeling and simulation technique developed to assist in the design and analysis of complex man-machine systems. SAINT consists of a symbol set for modeling systems and a computer program for analyzing such models. SAINT provides the conceptual framework

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for representing systems that consist of discrete task elements, continuous state variables, and interactions between them. While SAINT was designed for modeling manned systems in which human performance is a major concern, it is potentially applicable to a broad class of systems--those in which discrete and continuous elements are to be portrayed and quantified and whose behavior exhibits time-varying properties. SAINT provides a mechanism for describing these dynamics so a systematic assessment can be made of the relative contribution system components make to overall system performance. This report is intended as a procedural manual and reference guide for those persons already having some knowledge of the basic SAINT concepts and symbol set. Some of the topics covered are: (1) preparation of input data, (2) a description of the functions performed by the user-written subprograms included in SAINT, (3) the procedures for using the available user support programs, (4) a listing of the errors which SAINT can detect along with their probable causes, and (5) information concerning the operation and structure of the SAINT program itself.

#### SUMMARY

This report describes the procedures for using the SAINT simulation program to analyze system models. SAINT (Systems Analysis of Integrated Networks of Tasks) is a network modeling and simulation technique designed to aid the system designer and human engineer in analyzing complex man-machine It provides the conceptual framework which allows the development of system models in which men, machines, and the environment are represented. It permits the assessment of the effect of the component characteristics of the system on overall system performance. The symbolism and terminology required for modeling systems using (SAINT are introduced and described in Simulation Using SAINT: A User-Oriented Instruction Manual (1). The overall structure and individual FORTRAN subprograms of SAINT are described in Documentation for the SAINT Simulation Program (2). The use of an external statistical analysis package to analyze SAINT output is described in Analyzing SAINT Output Using SPSS (3).

In this manual, the SAINT symbol set and terminology that are presented in detail in <u>Simulation Using SAINT</u>: <u>A User-Oriented Instruction Manual</u> (1) are summarized. The preparation of input data and the organization of the input deck are described. The functions performed by the user-written subprograms included in SAINT are defined. The procedures for using the available user support subprograms are presented. The errors that SAINT can detect, as well as the probable cause of each error, are provided. Information concerning the operation and structure of the SAINT simulation program is also presented.

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#### PREFACE

This study was initiated by the Human Engineering Division, Aerospace Medical Research Laboratory, Wright-Patterson Air Force Base, Ohio 45433. The research was conducted by Pritsker & Associates, Inc., P. O. Box 2413, West Lafayette, Indiana 47906. The work was performed in support of Project 7184 "Man-Machine Integration Technology," task 718413 "Man-Machine Models for System Performance Assessment." The research sponsored by this contract was performed between August, 1975 and December, 1976, under Air Force contract F33615-76-C-5012.

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#### SECTION I

#### INTRODUCTION

SAINT provides a unique and powerful capability for modeling and analyzing complex man-machine systems. The technique's conceptual framework allows the development of system models in which men, machines, and the environment are represented. This permits an analyst to investigate the impact of modifications to the man-machine-environment interface on overall system performance. In addition, such investigations can be performed without a major investment in equipment and time and without necessitating a commitment to prototype hardware development.

SAINT enables an analyst to input a description of the system to be analyzed. The system description includes the tasks performed by the resources, the precedence relations among tasks, the flow of information through the system, and the effects of environmental stressors on task performance. SAINT also allows the specification, evaluation, and monitoring of state variables which represent processes that change status continously over time. In addition, modeling capabilities are available for representing the dynamic interaction of tasks, resources, and state variables in an overall systems context.

The system description serves as input data to the SAINT simulation program. SAINT automatically performs an analysis of the model developed and provides summary information concerning resource utilization, task performance, state variable status, and a wide variety of other system performance measures. In addition, SAINT allows the user to develop his own special summary reports.

The SAINT simulation technique is documented in three manuals. Simulation Using SAINT: A User-Oriented Instruction Manual (1) provides an analyst with the modeling concepts necessary to build SAINT models. This manual, The SAINT User's Manual, contains all of the information necessary to use the SAINT simulation program to analyze SAINT models. It is designed to be used after the SAINT modeling concepts are understood. Documentation for the SAINT Simulation Program (2) serves as a complete reference guide to the inner workings of the SAINT simulation program.

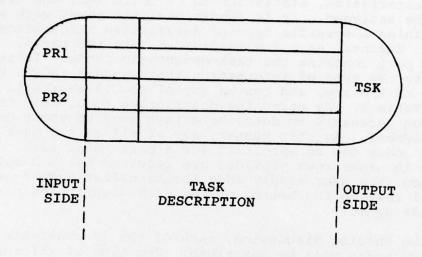
#### SECTION II

#### SAINT SYMBOLISM

The basic element of a SAINT network is a task. The symbol used to portray tasks in a SAINT model is shown in Figure 1. Three basic functions are associated with each task in a SAINT network: 1) release of the task (satisfying all predecessor requirements); 2) performance of the task and associated operations; and 3) identification of potential successor tasks. These three functions are described by an input side, a task description, and an output side. Each portion of the task symbol will now be described.

## Task Input

The number and nature of predecessor requirements for the release of a task are shown on the input side of the task symbol. The number of predecessor completions required for first release of the task (PR1) is at the top, while the number of predecessor completions required for subsequent release of the task (PR2) is at the bottom.



TSK	task number
PRl	number of predecessor completions required for first release of the task
PR2	number of predecessor completions required for subsequent release of the task

Figure 1. Task Symbol.

## Task Description

The center portion of the task symbol shown in Figure 1 contains all task description information; such as performance time characteristics, statistics to be collected, and attributes to be assigned. It is subdivided into rows, with each row containing a specific type of descriptive information about the task. Further, each row is divided into two parts. left-hand part contains the task description code. It is used to identify the type of information that appears in the righthand part of the row, and can be any of the 17 available codes shown in Table 1. By using the description code, only the information necessary to describe a task need be shown on the task symbol. In this manner, any or all of the task description codes can be specified for a particular task. more than the four rows provided are required for a complete description, the user simply adds the necessary number of additional rows to the bottom of the task description portion of the task symbol.

In the ensuing discussion, each of the 17 available task description codes will be described. The type of information that is identified by the code will be defined. In addition, examples will be shown that demonstrate the use of each code in describing a task. However, remember that the examples are only intended as guidelines. The SAINT user should employ a format that is convenient for his modeling and communication purposes. Caution should be exercised in developing new formats, as it is desirable that other SAINT modelers be able to read the network and understand the model. Many of the task description rows correspond to SAINT input cards. Thus, a trade-off exists between the ease of preparing SAINT input cards from the network model and the ease of communicating the characteristics of the SAINT model to others.

#### ATAS

The code ATAS identifies a row containing the attribute assignments to be made at the task. For example, if information attribute 2 is to be assigned a value drawn from distribution set 3 at the time the task is completed, then the ATAS row could appear as

ATAS	COM:	IA,2=DS,3	

However, if the value of attribute 4, resource 7, is to be

TABLE 1

TASK DESCRIPTION CODES

Description Code	Information Required by Description Code
ATAS	attribute assignments to be performed
DIFF	different predecessor option
DMOD	distribution set modifications to be made
INCM	information choice mechanism decision mode
LABL	label associated with task
MARK	marking information
MODF	moderator functions to be applied to task performance
PREC	completion precedence
PRTY	priority
RCLR	resource clearing to be performed
REGL	regulation to be performed
RESR	resource requirements
STAT	statistics to be collected
SWIT	switching to be performed
TCLR	task clearing to be performed
TIME	performance time characteristics
UTCH	user-defined task characteristics

assigned a value calculated in user function 11 at the start of the task, then the ATAS row could appear as

ATAS	START:	RA,7-4=UF,11	

If both assignments described above are to be made when the task is released, then the ATAS row could appear as

ATAS	REL:	(IA,2=DS,3),(RA,7-4=UF,11)

## DIFF

The code DIFF identifies a row containing the different predecessor requirements of the task. If different predecessor completions are required in order for the task to be released, then the DIFF row could appear as

DIFF	YES	

If different predecessors are not required, the DIFF row could be left out of the task description or could appear as

	T
DIFF	NO

## DMOD

The code DMOD identifies a row containing the distribution set modifications to occur upon completion of the task. If distribution set 3 is to be replaced by distribution set 5, then the DMOD row could appear as

DMOD	3 → 5		

or as

DMOD	DS,3 →	DS,5	

## INCM

The code INCM identifies a row containing the information choice mechanism decision mode. If the information packet arriving with the first predecessor completion is to be saved, then the INCM row could appear as

INCM	FIRST

If the information packet with the smallest value of attribute 2 is to be saved, then the INCM row could appear as

INCM	SMALL,2

#### LABL

The code LABL identifies a row containing the label assigned to the task. On the network, the task label can be of any length. However, only eight alphanumeric characters are recognized by the SAINT input processor.

Assume that a task represents the action of traveling to a desired location. A task description row could then appear as

	mpatrer.	mo	ATTITUTE.	TOGRATON	
LABL	TRAVEL	TO	NEW	LOCATION	

## MARK

The code MARK identifies a row containing marking information. If marking is to take place at the time of release of the task, then the MARK row could appear as

MARK	RELEASE

If the marking is to take place upon completion of the task, then the MARK row could appear as

MARK	COMPLETION

or as

MARK	COM	

## MODF

The code MODF identifies a row containing the moderator functions to be applied to task performance. For example, if moderator function 1 represents a speed function and moderator function 5 represents an environmental-related function, and both are to be applied to this task, then the MODF row could appear as

MODF	1,5	CONTRACT CONTRACTOR

or as

MODF	1 (SPEED), 5 (ENVIRONMENT)

## PREC

The code PREC identifies a row containing the task completion precedence value. If two tasks are completed at the same time, the task with the higher PREC value will be processed first. If the completion precedence is 15, then the PREC row could appear as

PREC	15.

## PRTY

The code PRTY identifies a row containing the task priority used for scheduling purposes. If the priority of the task is 5, then the PRTY row could appear as

PRTY	5.	

#### RCLR

The code RCLR identifies a row containing the resources to be cleared and the associated tasks to be signaled upon task completion. If resource 1 is to be cleared and task 53 is to be signaled, and resource 5 is to be cleared and no task signaled, then the RCLR row could appear as

RCLR	(CLR	1,SIG	53), (CLR	5)

or as

RCLR	(C1,S53),(C5,NO SIGNAL)
------	-------------------------

#### REGL

The code REGL identifies a row containing the state variable regulation to be performed upon task completion. If the value of SS(16) is to be set to 5.\*SS(4)+3, then the REGL row could appear as

REGL	SS(16) →	5.*SS(4)+3.	

If the value of SS(16) is to be decreased by the same regulating

function, then the REGL row could appear as

REGL	SS(16)	+	5.*SS(4)+3.
------	--------	---	-------------

## RESR

The code RESR identifies a row containing the resource requirements of the task. If the task requires resources 1, 5, and 7 for performance, then the RESR row could appear as

RESR	AND:	1,5,7

or as

RESR	AND:	1 (PLUMBER), 5 (HAMMER), 7 (WRENCH)
TUDDIC	11110.	I (I DOMBER) , 3 (MARKER) , / (WILLIACIT)

If the task requires only one resource, and it must be either resource 2 or resource 3, then the RESR row could appear as

RESR	OR.	2,3	
TUDDIC	on.	2,5	

#### STAT

The code STAT identifies a row containing the statistics to be collected at the task. For example, assume that statistics are to be collected on the time between starts of the task. Further assume that the histogram to be generated contains 25 cells, with the upper limit of the first cell being 20 and the cell width being 15. Then the STAT row could appear as

STAT	BETWEEN STARTS	
		-

or as

or as

STAT	BET STA	(25.,20.,15.)

## SWIT

The code SWIT identifies a row containing the switching to be performed upon task completion. If the value of switch 3 is to be set to 152, then the SWIT row could appear as

		7
SWIT	IS,3=152	1

or as

SWIT	SET	SWITCH	3	TO	152	
------	-----	--------	---	----	-----	--

## TCLR

The code TCLR identifies a row containing the tasks to be cleared and the associated tasks to be signaled upon task completion. For example, if task 27 is to be cleared and task 39 is to be signaled upon completion of this task, then the TCLR row could appear as

TCLR	27,39
	The other interests of a section of the section of

or as

TCLR	CLEAR 27,SIGNAL 39

## TIME

The code TIME identifies a row containing the performance time characteristics. If the task time is located in distribution set 3, then the TIME row could appear as

TIME	DS,3

or as

TIME	DS,3	(NORMAL, MEAN=5.75)

If the task performance time is located in attribute 5 of resource 1, then the TIME row could appear as

TIME	RA,1-5

## UTCH

The UTCH code identifies a row containing the user-defined task characteristics of the task. If the task requires user-defined task characteristics 1, 5, and 6; and they have values of 2.75, 1.9, and 2, respectively; then the UTCH row could appear as

UTCH	(1,2.75),(5,1.9),(6,2.)

## Examples of Task Descriptions

In the previous discussion, definitions and examples of the 17 available description codes were presented. The following examples show how the individual description rows can be integrated to form a complete task description.

## Example 1

	LABL	FIX SINK	1
/ 1	TIME	DS,3	)
	RESR	AND: 1,3,5	5
1	MODF	1,7	

Task 5 represents the operation of fixing a sink. The baseline time to perform the task is a deviate drawn from distribution set 3. It is to be performed with resources 1, 3, and 5. Moderator functions 1 and 2 are to be applied to task performance.

## Example 2

2	TIME	RA,3-15	
/ -	ATAS	COM: IA,5=UF,4	
2	STAT	COM: INTERVAL	27
1	SWIT	S5=20	
. 603	DIFF	YES	Argon I may

The time to perform task 27 is located in attribute 15 of resource 3. Upon completion of the task, information attribute 5 is to be assigned a value calculated in user function 4. Interval statistics (time since the last marking) are to be collected upon task completion. Finally, the value of switch 5 is to be set to 20. In addition, different predecessor completions are required in order for the task to be released.

## Example 3

/	TIME	UF,18	1
0	PRTY	129.23	_ \
\	MARK	REL	54
	RCLR	(1,15),(5,23)	
	REGL	SS(4) ↑ SS(27)+3.25	

The time to perform task 54 (a source task, since it requires no predecessor completions for release) is calculated in user function 18. The priority for scheduling purposes is 129.23. Marking is to take place when the task is released. When task 54 is completed, resources 1 and 5 are to be cleared, and tasks 15 and 23 are to be signaled. In addition, SS(4) is to be increased in value by SS(27)+3.25.

## Example 4

	TIME	SC,10	
/ 10	INCM	BIG,11	
100	PREC	10.	
700	UTCH	(1,2.75),(2,157.)	
	DMOD	DS,10 → DS,21	
	TCLR	C35,S14	

Task 17 takes 10 time units to perform. The information packet with the biggest value of attribute 11 will be saved. The completion precedence is 10. The value assigned to user-defined task characteristic 1 is 2.75, and the value of user-defined task characteristic 2 is 157. When the task is completed, distribution set 10 is replaced by distribution set 21, task 35 is cleared, and task 14 is signaled.

#### Task Output

Each task in a SAINT network is uniquely identified by a task number shown on the output side of the task symbol. The shape of the output side indicates the type of branching operation to be performed upon task completion (deterministic, probabilistic, conditional-take first, or conditional-take all). The symbols for the four types of branching operations available in SAINT are shown in Table 2. Tables 3 and 4 define and present examples of the branch codes for probabilistic and conditional branching. Deterministic branching requires no branch codes.

TABLE 2

# AVAILABLE BRANCHING TYPES

Branching Type  Deterministic	Symbol	Description of Branching Operation  All branches emanating from this task will be selected.
Probabilistic		One and only one of the branches emanating from this task will be selected. The selection is made on a random basis using the probabilities associated with the branches.
Conditional- Take First		One and only one of the branches emanating from this task will be selected. The branches are rank ordered and the associated conditions are tested. When one of the conditions is satisfied, the associated branch is selected.
Conditional- Take All		All branches whose conditions are satisfied will be selected. As with conditional-take first branching, the branches are rank prdered and the associated conditions are tested. All branches emanating from the task are tested for possible selection.

TABLE 3
PROBABILISTIC BRANCHING CODES

Branch Code	Description
(p)	Probability of selection equals p
(T,A)	Probability of selection equals the value of attribute A of type T

## Examples of the branch codes are:

(0.75)	Probability of selecting branch is 0.75
(IA,7)	Probability of selecting branch is the value of information attribute 7
(RA,5-3)	Probability of selecting branch is the value of resource 5, attribute 3
(SA, 25)	Probability of selecting branch is the value of system attribute 25

# CONDITIONAL BRANCHING CODES

Branch Code	Description of Condition for Selecting Branch
(TLV,x)	TNOW. LE. x
(TGV,x)	TNOW.GT.x
(TLA,T,A)	TNOW.LE.V(T,A)
(TGA,T,A)	TNOW.GT.v(T,A)
(TVC,N)	Task N has been completed
(TVN,N)	Task N has not been completed
(TAC,T,A)	Task identified as v(T,A) has been completed
(TAN,T,A)	Task identified as v(T,A) has not been completed
(ALV,T,A,x)	v(T,A).LE.x
(AGV,T,A,x)	v(T,A).GT.x
(ALA,T,A,B)	v(T,A).LE.v(T,B)
(AGA,T,A,B)	v(T,A).GT.v(T,B)

Definitions of the terms used in the descriptions are:

TNOW	<pre>current simulation time (time of task completion)</pre>
.LE.	"less than or equal to"
.GT.	"greater than"
x	specified real value
V(T,A)	value of attribute A of type T
v(T,B)	value of attribute B of type T

## Examples of the branch codes are:

(TLV, 5.75) Select branch if time of task completion is less than or equal to 5.75 (TGA, IA, 7) Select branch if time of task completion is greater than the value of information attribute 7 (TVC, 35) Select branch if task 35 has been completed (TAN, RA, 4-1)Select branch if the task whose number is the value of resource 4, attribute 1, has not been completed Select branch if the value of system attri-(ALV, SA, 12, 2.3) bute 12 is less than or equal to 2.3 (AGA, IA, 3, 5)Select branch if the value of information attribute 3 is greater than the value of information attribute 5

## Additional Task Modeling Concepts

Task modification involves the substitution of the task description and output side of one task for those of another task. The illustration in Figure 2 indicates that task 8 will be replaced by task 9 upon completion of task 2 (the symbol  $\triangle$  identifies a task modification operation).

Task and resource clearing involve the interruption (clearing) of a task in progress when another task is completed. If a clearing operation is performed, SAINT allows the number of predecessor requirements for another task to be reduced by one (signaling). As indicated previously, the clearing information is included as a part of the description of the task whose completion causes the clearing. The illustration in Figure 3 indicates that task 37 is to be signaled as a result of the clearing caused by the completion of task 5 (the symbol ) identifies a task signaling operation caused by a task or resource clearing).

SAINT also allows the number of predecessor requirements for a task to be reduced by one as a result of a threshold crossing detected by a monitor. Figure 4 illustrates a situation in which task 20 will be signaled when monitor 10 detects a threshold crossing (the symbol identifies a task signaling operation caused by a threshold crossing).

#### State Variable Definitions

Although the SAINT user must set the initial values of state variables in subroutine INTLC and code their defining equations in subroutine STATE; symbolism is available to define state variables on the network model. For each state variable included in a SAINT model, four pieces of information are defined: state variable number, state variable label, defining equation in STATE, and initial value in INTLC. State variable information is depicted on the network model in the manner shown in Figure 5.

#### Monitors

The symbol which is used to represent a state variable monitor in a SAINT model is shown in Figure 6. Its design is similar to that provided for task descriptions. The right-hand side of the symbol contains the monitor description, and is divided into four rows. Each row represents a unique type of descriptive information, and is identified by one of the following description codes: LABL, MONF, MTAS, and MSWT. By using the description codes, only the information necessary to describe a monitor need be shown on the monitor symbol. Each code will be defined and examples of their use presented in the following discussion.

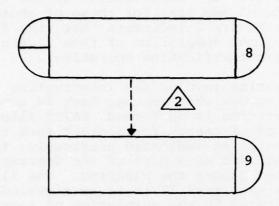


Figure 2. Task Modification.

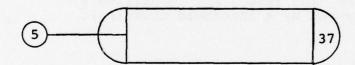


Figure 3. Task Signaling as a Result of Task or Resource Clearing.

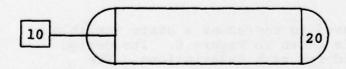


Figure 4. Task Signaling as a Result of Threshold Crossing.

State Variable Number	State Variable Label	Defining Equation in STATE	Initial Value in INTLC
1	PRESSURE	DD(1)=SS(3)	5.2
2	ACCELERATION	DD(2)=4.*SS(1)	0.
3	OIL LEVEL	-	5.
4	STRESS	SS(4)=SSL(4)+DTNOW*(1-LEVEL)	7.39
5	POSITION	SS(5)=SSL(5)+POS*DTNOW	27.5

Figure 5. State Variable Information on Network Model.

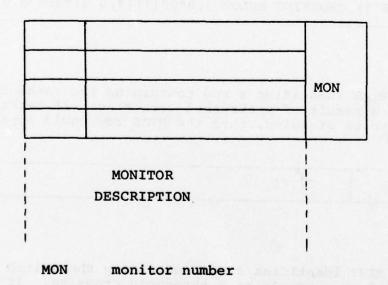


Figure 6. State Variable Monitor Symbol.

#### LABL

The code LABL identifies a row containing the monitor label. For example, if pressure is being monitored, then the LABL row could appear as

LABL	PRESSURE

## MONF

The code MONF identifies a row containing the function to be used in locating the threshold crossing. For example, suppose that the value of SS(1) is being monitored. A threshold crossing occurs when the value of SS(1) falls below the value of 3.0\*SS(7)+4.0 within a tolerance of 0.05. The MONF row could appear as

MONF	ss(1) ¥	3.0*SS(7)+4.0(TOL=.05)

or as

1	00/31	CROCCING	DEL ON	2 0+00(7) 14 0	LITMITAL	0.05
MONF.	SS (1)	CROSSING	BETOM	3.0*SS(7)+4.0	MITHIN	0.05
and of the second second						

#### MTAS

The code MTAS identifies a row containing the tasks to be signaled as a result of a threshold crossing. If tasks 27 and 41 are to be signaled, then the MTAS row could appear as

MTAS	27,41
------	-------

## MSWT

The code MSWT identifies a row containing the switch values to be set as a result of a threshold crossing. If the value of switch 3 is to be set to 27, then the MSWT row could appear as

IS,3=27

or as

ACT.TO	CDM GUTMOU 3 MO 37	
MSWT	SET SWITCH 3 TO 27	

## Example of Monitor Description

In the previous discussion, definitions and examples of the four available description codes were presented. The following example shows how the individual description rows can be integrated to form a complete monitor description.

LABL	SOLUTION CONCENTRATION	15
MONF	SS(3) A SS(10)+17.2,TOL-0.5	
MTAS	35	
MSWT	(IS,1-3),(IS,5=40)	

The example shown above is the symbol describing monitor 15. The state variable being monitored, SS(3), is the concentration of a solution. When the concentration increases beyond the value of SS(10)+17.2, with a tolerance of 0.5, a threshold crossing occurs. This causes task 35 to be signaled, switch 1 to be set to 3, and switch 5 to be set to 40.

This concludes the discussion of monitor symbolism. Note that only those rows necessary to completely describe the monitor need be shown on the monitor symbol.

#### SECTION III

#### SAINT DATA INPUT PROCEDURE

The SAINT simulation program is a FORTRAN program for simulating SAINT models. The user of SAINT need only master the procedures for translating a model into data input cards in order to obtain an analysis of the model. This section specifies the procedures involved in this translation. It provides the complete specifications for preparing the input to the SAINT program. A list of the SAINT data types is presented in Table 5. The procedures for data input card preparation are described next. This is followed by a detailed description of each data type and their corresponding input fields. A condensed version of the data type descriptions is included at the end of this section for the user who is familiar with the detailed description.

# Data Input Card Preparation

All SAINT data input is prepared in free format. Free format input permits information to be punched without card column restrictions, where each input variable is defined as a field of the data input card. The features of SAINT free form input include:

- Card ID Free form data cards are uniquely identified by an ID specified in the first field of the card. Only the first three characters on this ID are significant. Valid card types are identified in Table 5.
- Blanks Leading blanks and blanks imbedded in numeric fields are ignored.
- 3. Field Termination All fields on a card except the last are terminated by commas.
- 4. Continuation Cards Continuation cards are permitted. If the last non-blank character of a card is a comma, it is assumed that additional fields of the input record are contained on the card which follows. Fields may not be split between cards. A continuation card contains no card ID and the additional fields may be punched anywhere in the card. Continuation cards may themselves be continued. However, an input record may not exceed 50 fields.
- Record Termination An asterisk should be punched after the last field of an input card. If no asterisk is present and the last non-blank character in the

# TABLE 5 LIST OF SAINT INPUT DATA TYPES

# General Information

GEN	General Information
SGE	State variable general information
POP	Program options
OUT	Output options
DIS	<u>Dis</u> tribution set definitions
SIM	Used when multiple networks are to be <u>simulated</u> to mark the end of input for each network except the last
FIN	Signals end (finish) of all SAINT input cards

# User-Generated Statistics and Plots

UBO	User-generated statistics for variables $\underline{b}$ ased on $\underline{o}$ bservation
UTI	User-generated statistics for $\underline{\text{time-persistent}}$ variables
UHI	<u>User-generated histograms</u>
UPL	User-generated plot/table characteristics
UVA	User-generated plot/table variable information

# Initial Status and Labels

IMO	<u>Initial</u> <u>moderator</u> function status specification
IRA	Initial resource attribute specification
ISA	Initial system attribute specification
LRE	Labels for resources
LSV	Labels for state variables

# Task Description

TAS Task characteristics

STA Statistics task information

UTC Specification of user-defined task character-

istics

MOD Specification of moderator function status

ATA Specification of attribute assignment infor-

mation

# Task Branching

DET Deterministic branching

PRO Probabilistic branching

CFI Conditional-take first branching

CAL Conditional-take all branching

#### Effects of Task Completions

NMO Network modifications

DMO Distribution set modifications

TCL Task clearing

RCL Resource clearing

SWI Switching information

REG Regulation information

#### State Variable Monitors

MON Monitor characteristics

MTA Monitor actuated task signaling

MSW Monitor actuated switching

# State Variable Statistics and Plots

SST	<u>S</u> tate	variable	<u>st</u> atistics	information
PLO	State	variable	plot/table	characteristics
VAR	State tion	variable	plot/table	variable informa-

card is not a comma, then an end of input record is assumed. The use of an asterisk is preferred since it reduces scanning time.

- 6. Alphanumeric Information Alphanumeric data may begin with a letter or a digit and may contain any combination of letters and digits. In any alphanumeric field, characters which are not significant or required for that field may be included for clarity and documentation purposes, but will be ignored in processing. Alphanumeric fields contain at most 8 significant characters.
- 7. Numeric Information Any numeric information may be input as an integer or as a real number.
  - a. If an integer is input for a field specified as real, the real equivalent of the integer value is used.
  - b. If a real is input for a field specified as integer, the decimal portion of the real field is truncated and the integer equivalent of the truncated result is used.

Real values may also be input as E-format ("floating-point") numbers. A valid E-format field consists of a number followed by the letter E and a one or two digit power of 10. The number may be signed or unsigned. The exponent must not contain a decimal point and may be signed or unsigned. (Largest valid exponent is machine dependent.) Integers and E-format reals are not interchangeable. A warning message will be generated if an E-format real is submitted for a field which should contain an integer.

#### Examples:

+53.9E+10 53.9E10 53.9 E-10 .539E -8 1.E20 -1.0E+20

- 8. Default Values Default values are defined for all nonessential input fields. To indicate that the default value is to be used for a certain field (or that a field is not applicable in a given context), the user should do one of the following:
  - a. Omit the field Omission of a field is

indicated by a comma or by blanks followed by a comma.

b. Skip to the next user-specified input field If the user lists the number (enclosed in
parentheses) of the next field for which he
wishes to specify information, all intermediate fields will be bypassed and will assume
default values. For example, if the following card is input

POP, 4,,5,(8) MULTIPLE\*

these assumptions will be made:

field 1 = POP

field 2 = 4

field 3 will assume a default value

field 4 = 5

fields 5.through 7 will assume default values

field 8 = M

field 9 will assume a default value

- c. Terminate the card before giving a value for the field. For instance, in the preceding example field 9 assumes a default value since nine fields are associated with card type POP and only eight values were specified on the input card.
- 9. Deck Setup Cards for a single network may be input in any order with the following exceptions:
  - a. GEN, SGE (if any), POP, OUT, and DIS cards must be input before any other card types.
  - b. VAR cards must follow their associated PLO card. Similarly, UVA cards must follow their associated UPL card.
  - c. A SIM or a FIN card must be the last input card for a network. (A SIM card is used if input for an additional network follows.)

Only those cards which will be used for a particular network need to be input. For example, if no network modifications or task clearings are included in the model, no NMO or TCL cards should be submitted.

SAINT networks can be sequentially analyzed by stacking the data cards for each network one after another. A SIM card should separate the data cards for each network.

#### Detailed Description of Data Types

Each data type will not be presented. For each field in a data card, the field number, the nature of the input (A=alphanumeric, I=integer, R=real), the associated default values (if any), and a description of field contents will be listed. In the specification of alphanumberic inputs, the required characters for each code are underlined in the description of the code if not all characters shown are required.

GEN - General Information

Field	Value	Default	Description
1	A		Card identification (GEN).
2	A	SAINT	User name (maximum of 8 characters).
3	I	1	Month.
4	I	1	Day.
5	I	2001	Year.
6	I	1	Project number.
7	I	1	Number of iterations.
8	I	1	Number of sink tasks that must be completed for network to be completed.
9	I	71268659	Integer random number seed.
10	R	1.	Scale factor to be used in conjunction with function type SC.
11	A	Y	Print suppression key: Yes = Print echo check. No = Skip printing of echo check.

SGE - State Variable General Information

This data type is input only if state variables ar

This data type is input only if state variables are defined for the simulation.

Field	Value	Default	Description
1	A		Card identification (SGE).
2	Ι	0	Number of equations (largest index) defining state variables written in terms of DD(·). (NNEQD)
3	I	0	Number of equations defining state variables written in terms of SS(·). (NNEQS)
4	R	(.01*DTMAX)	Minimum step size permitted (DTMIN).
5	R	(Min (DTSAV, 1.E20)	)) Maximum step size permitted (DTMAX).
6	R	1.E20	Communication interval for re- cording values on plots/tables (DTSAV) >0 Time between communication points =0 Communication to occur at each accepted update point <0 Communication only at event times
7	R	.00001	Absolute local truncation error allowed in Runge-Kutta integration. (AAERR)
8	R	.00001	Relative error allowed in Runge- Kutta integration. (RRERR)
9	A	W	Key to indicate severity of error when accuracy cannot be maintained by the Runge-Kutta integration package, either in state variable updates or searching for threshold crossings.  None - Proceed without warning message Warning - Proceed with warning message Fatal - Fatal error Accuracy is required to be less than or equal to absolute error + (relative error *SS(I)) for all I.

POP - Program Options

Field	Value	Default	Description
1 .	A		Card identification (POP).
2	I	0	Number of resources involved in the simulation (largest resource number).
3	I	0	Number of resource attributes desired per resource packet.
4	I	0	Number of information attributes desired per information packet.
5	I	0	Number of system attributes desired.
6	I	0	Number of moderator functions desired.
7	A	I	Network Modifications (if any) Interchange - Interchange modifications desired Multiple - Multiple replacement
			modifications desired
8	Α		Distribution Set Modifications (if any)  Interchange - Interchange modifications desired  Multiple - Multiple replacement modifications desired.
9	I	3	Ranking procedure for the file of tasks awaiting scheduling  1 Low value first on priority 2 High value first on priority 3 First-in, First out (FIFO) 4 Last-in, Last-out (LILO)

<u>OUT</u> - Output Options

Field	Value	Default	Description
1	A		Card identification (OUT).
2	I	0	Iteration number for which the detailed output should begin.
3	I	value in field 2	Iteration number for which the detailed iteration output should terminate.
4	I	0	Iteration number for which the resource utilization summary output should begin.
5	I	value in field 4	Iteration number for which the resource utilization summary output should terminate.
6	I	0	Iteration number for which the statistics task summary output should begin.
7	I	value in field 6	Iteration number for which the statistics task summary output should terminate.
8	I,	0	Iteration number for which initial and final state variable value outputs should begin.
9	I	value in field 8	Iteration number for which initial and final state variable value outputs should terminate.
10	I	0	Iteration number for which state variable statistical output should begin.
11	I	value in field 10	Iteration number for which state variable statistical output should terminate.
12	I	0	Iteration number for which the preparation of state variable plots/tables should begin.

Field	<u>Value</u>	Default	Description
13	I Dies is	value in field 12	Iteration number for which the preparation of state variable plots/tables should terminate.
14	A	Y	Print suppression key:  Yes = Print resource utilization summary report.  No = Do not print report.
15	A	Y min	Print suppression key:  Yes = Print statistics task summary report.  No = Do not print report.
16	A	N	Print suppression key:  Yes = Print histograms of statistics tasks values from iteration 1.  No = Do not print histograms.
17	A	N	Print suppression key:  Yes = Print histograms of statistics tasks values from summary report.  No = Do not print histograms.

# DIS - Distribution Set Definitions

All distribution sets required for task performance times and attribute assignments are defined by these input cards. One card is required for each different distribution set number.

Field	Value	Default	Description
1	A		Card identification (DIS).
2	I		Distribution set number.
3	A	CO	Distribution type (maximum of 2 characters).
4-7	R	0.	Parameter values for the distri- tion specified in Field 3 as defined by the following input description.

## Available SAINT Distributions

In SAINT, sample values can be obtained from any of the following 11 distributions:

- BE Beta
- BP Beta fitted to 3 values as in PERT
- CO Constant
- ER Erlang (includes Exponential)
- GA Gamma
- LO Lognormal
- NO Normal
- PO Poisson
- TR Triangular
- UN Uniform
- WE Weibull

#### Parameters Required for SAINT Distributions

In SAINT, samples are obtained from the distributions such that if a sample is less than the minimum value, the sample value is assigned the minimum value. Similarly, if the sample is greater than the maximum value, the sample value is assigned the maximum value. This is not sampling from a truncated distribution, but sampling from a distribution with a given probability of obtaining the minimum and maximum values.

The parameters required to sample from the distributions available in SAINT are described below. Fields 1, 2, and 3 are the same for all distributions.

# For distribution type CO (Constant):

#### Field 4 The constant time

# For distribution type NO (Normal); LO (Lognormal); BE (Beta); and GA (Gamma):

- Field 4 The mean value
- Field 5 The minimum value
- Field 6 The maximum value
- Field 7 The standard deviation value

# For distribution type UN (Uniform):

Not used Field 4

Field 5 The minimum value

Field 6 The maximum value

Field 7 Not used

# For distribution type ER (Erlang):

The mean time for the Erlang variable divided by the Field 4 value given to Field 7

Field 5 The minimum value

Field 6 The maximum value

Field 7 The number of exponential deviates to be included in the sample obtained from the Erlang distribution

If Field 7 is set equal to 1, an exponential deviate will be obtained from distribution type ER.

## For distribution type PO (Poisson):

The mean minus the minimum value

Field 5 The minimum value

Field 6 The maximum value

Field 7 Not used

Care is required when using the Poisson since it is not usually used to represent an interval of time.

# For distribution type BP (Beta fitted to 3 values as in PERT); TR (Triangular):

Field 4

The most likely value, m
The optimistic (smallest) value, a Field 5

The pessimistic (largest) value, b Field 6

Field 7 Not used

# For distribution type WE (Weibull):

Field 4  $\alpha (\alpha > 0)$ 

Field 5 The minimum value

Field 6 The maximum value

Field 7  $\beta$  ( $\beta$  > 0)

#### where:

$$f_{x}(x) = \alpha \beta x^{\beta-1} e^{x} p[-\alpha x^{\beta}], \text{ and}$$

$$F_{\mathbf{v}}(\mathbf{x}) = 1 - \exp[-\alpha \mathbf{x}^{\beta}]$$

<u>UBO</u> - User-Generated Statistics for Variables Based on Observation.

This card type is required for user-generated statistics for variables based on observation.

Field	Value	Default	Description
1	A		Card identification (UBO).
2	I	168609 01 604700008	Statistic number (used as an argument to subroutine UCLCT).
3	A	""	Statistic label (maximum of 8 characters).

Fields 2 and 3 may be repeated so that up to 24 statistics may be specified in a single input record. Additional UBO cards may also be used.

UTI - User-Generated Statistics for Time Persistent Variables
This card type is required for user-generated statistics
for time-persistent variables.

Field	Value	Default	Description
1	A		Card identification (UTI).
2	I		Statistic number (used as an argument to subroutine UTMST OR UTMSA).
3	A	""	Statistic label (maximum of 8 characters).
4	R	0.	Initial value of the variable to be observed.

Fields 2 - 4 may be repeated so that up to 16 statistics may be specified in a single input record. Additional UTI cards may also be used.

<u>UHI</u> - User-Generated Histograms

This card type is required for user-generated histograms.

Field	<u>Value</u>	Default	Description
1	A	ned <u>lille</u> bed	Card identification (UHI).
2	I		Histogram number (used as an argument to subroutine UHIST).
3	A	""	Histogram label (maximum of 8 characters).
4	I	25	Number of cells in histogram.
5	R	0.	Upper limit of first cell of histogram.
6	R	1.	Width of each cell of histogram.

Fields 2 - 6 may be repeated so that up to 9 histograms may be specified in a single input record. Additional UHI cards may also be used.

# User-Generated Plots/Tables

User-generated plot/table information is contained on two types of data cards. The first card (UPL card) contains information on the plot/table. The second card (UVA card) contains information on the variables to be plotted/tabled. One or more UVA cards may be input to describe the variables to be included in the plot/table described by UPL card. One UPL card and its associated UVA cards are required for each user-generated plot/table.

UPL - User-Generated Plot/Table Characteristics

<u>Field</u>	Value	Default	Description
1	A	402 <b></b>	Card identification (UPL).
2	I		Plot/table number (used as an argument to subroutine UPLOT).
3	A	"TIME"	<pre>Independent axis label (maximum of 8 characters).</pre>
4	A	0	Storage medium to be used for plot/table values:
			Peripheral storage unit number on which plot/table information is to be written (required if multiple plots/tables are desired).
			<pre>= 0 Plot/table information to be stored in core (UPSET(•)). Only 1 plot/table can be re- quested and Field 2 must be set to 1 if core is used.</pre>
5	A	P	Plot/table option
			Quick - Quick Plot Plot - Plot only Table - Table only Both - Plot and table.
6	R	5.	Increment of the independent variable between successive plot points.

<u>UVA</u> - User-Generated Plot/Table Variable Information

Field	<u>Value</u>	Default	Description
1	A		Card identification (UVA).
2	I		Plot/Table Number (same as Field 2 of associated UPL card).
3	I		Variable number.
4	I	value in field 3	Plot symbol (maximum of 1 character).
5	A	""	Label associated with the variable being plotted/tabled (maximum of 8 characters).
6	A	M	Key for specifying the lower limit of the scale to be used for the variable  Minimum - Use minimum value observed during the simulation.  Value - Use value in Field 8.  Rounded - Use the largest multiple of the value specified in Field 8 that is less than or equal to the minimum value observed.
7	A	М	Key for specifying the upper limit of the scales to be used for this variable  Maximum - Use maximum value observed during the simulation.  Value - Use value in Field 9.  Rounded - Use the smallest multiple of the value specified in Field 9 that is greater than or equal to the maximum value observed.
8	R	0.	Value associated with the lower limit of the plot ordinate (see Field 6).

Field	Value	Default	Description
9	R	0.	Value associated with the upper limit of the plot ordinate (see Field 7).

Fields 3 - 9 may be repeated so that up to 6 variables may be described on a single data card. Additional UVA cards may also be used to describe additional variables.

IMO - Initial Moderator Function Status Specification

Field	Value	Default	Description
1	A		Card identification (IMO).
2	I		Moderator function number.
3	A	I	Initial moderator function status Inactive - Moderator function inactive Active - Moderator function active.

Fields 2 and 3 may be repeated so that the initial status of up to 24 moderator functions may be specified on a single data card. Additional IMO cards may also be used to initialize additional moderator functions.

If the initial status of a moderator function is not specified by this data type, it is assumed to be inactive.

# IRA - Initial Resource Attribute Specification

This card is used to specify the initial resource attribute assignments. All assignments specified on a single data card are assigned to the resource whose number is specified in Field 2 of that card.

Field	Value	Default	Description
1	A		Card identification (IRA).
2	I		Resource number associated with all assignments specified on this card.
3	I		Resource attribute number to which the assignment specified in Fields 4 and 5 is to be made.
4	A	SC	The function to be used in conjunction with the parameter specification (Field 5) in making the assignment. The allowable functions are:  DS Value sampled from the distribution set specified as the parameter specification.  SC Constant equal to the parameter specification divided by the scale factor (Field 21 of GEN card).  UF User-written function (used in conjunction with function USERF (I) where I is the parameter specification).
5	I	0	Parameter specification to be used in making the assignment.

Fields 3 - 5 may be repeated so that up to 10 initial resource attribute assignments can be made on a single data card. Additional IRA cards may also be used to make additional initial resource attribute specifications.

ISA - Initial System Attribute Specification

<u>Field</u>	Value	Default	Description
1	A		Card identification (ISA).
2	I		System attribute number to which the assignment specified in Fields 3 and 4 is to be made.
3	A	sc	The function to be used in conjunction with the parameter specification (Field 3) in making the assignment. The allowable functions are:  DS Value sampled from the distribution set specified as the parameter specification  SC Constant equal to the parameter specification divided by the scale factor (Field 12 of GEN card)  UF User-written function (used in conjunction with function USERF(I), where I is the parameter specification).
4	I	0	Parameter specification to be used in making the assignment.

Fields 2 - 4 may be repeated so that up to 10 initial system attribute assignments can be made on a single data card. Additional ISA cards may also be used.

LRE - Labels for Resources
This card type is required to assign labels to resources.

<u>Field</u>	Value	Default	Description
1	A		Card identification (LRE).
2	I	are out to me	Number of the resource to be assigned a label.
3	A	""	Alphanumeric label for the resource specified in Field 2 (maximum of 8 characters).

Fields 2 and 3 may be repeated so that a total of 10 resource labels can be specified in a single input record. Additional LRE cards may also be used.

LSV - Labels for State Variables

This card type is required to assign labels to state variables.

<u>Field</u>	Value	Default	Description
1	A		Card identification (LSV).
2	I	300	Number of the state variable to be assigned a label.
3	A	""	Alphanumeric label for the state variable specified in Field 2 (maximum of 8 characters).

Fields 2 and 3 may be repeated so that a total of 10 state variable labels can be specified in a single input record. Additional LSV cards may also be used.

#### Task Definitions

Information about a task is contained on up to six data cards. The first card (TAS card) contains information about the characteristics of the task. The second card (STA card) contains information concerning marking and the statistics to be collected at the task. This card is only used if marking is to be performed or statistics are to be collected at the task. The third card (UTC card) contains the values of user-defined task characteristics. This card is only used if the number of user-defined task characteristics is greater than zero. The fourth card (MOD card) contains moderator function status information. This card is only used if any status changes are to be made. The fifth card (ATA card) contains attribute assignment information. This card is only used if attribute assignments are to be made. The sixth card contains information about the task's branching and successor tasks. A branching card is only used if branching is performed from the task. The following branching types are allowed:

deterministic (DET card)
probabilistic (PRO card)
conditional-take first (CFI card)
conditional-take all (CAL card)

TAS - Task Characteristics

Field	Value	Default	Description
1	A		Card identification (TAS).
2	I		The number of the task whose characteristics are given on this card.
3	A	""	Task Label (maximum of 8 characters).
4	I	0 if source tas 1 otherwise	k, The number of predecessor com- pletions required to release the task for the first time.
5	I	9999	The number of predecessor com- pletions required for all subse- quent releases of the task.
6	A	SC	The function to be used in conjunction with the parameter specification in Field 7 in obtaining the task performance time. The allowable functions are:  DS Value sampled from the distribution set specified as the parameter specification SC Constant equal to the parameter specification divided by the scale factor (Field 12 of GEN Card)  UF User-written function (used in conjunction with function USERF (I), where I is the parameter specification)  IA Value taken from the information attribute specified as the parameter specification  RA Value taken from the resource attribute specified as the parameter specification  SA Value taken from the system attribute specified as the parameter specification.
7	I	0	Parameter specification to be used in conjunction with Field 6 in obtaining a value for the task performance time.

Field	Value	Default	Description
8	and tit	0 953.60	Resource number to be used if function RA was selected in Field 6.
9	R	0.	Task priority.
10	A	NS	Special task characteristics SOurce - Source task SInk - Sink task NS - No special characteristic is associated with the task.
11	A	N	Indicator that different predecessor completions are required to release the task.  Yes - Different predecessor completions required  No - No requirement for different predecessor completions.
12	A		Information choice mechanism decision mode First - Hold packet arriving with first requirement Last - Hold packet arriving with last requirement Big - Hold packet with the largest value in attribute specified in Field 13 Small - Hold packet with the smal- lest value in attribute specified in Field 13.
13	I	0	Information attribute to be used for comparison if mode Big or Small is selected in Field 12.
14	R	0.	Task completion precedence.
15	Α	Α	Resource Requirement Code  And - All resources specified
16-20	I		Resources associated with this task (must appear in ascending numerical order; maximum of five resources permitted).

# STA - Statistics Task Information

This card is required only if marking is to be performed or statistics are to be collected at this task. Only one STA card per task is allowed.

Field	Value	Default	Description
1	A		Card identification (STA).
2	I		Task number.
3	A	N	<pre>Indicator that marking is to be performed at this task: M - marking N - no marking.</pre>
4	A	СОМ	Time of marking: FPC - first predecessor completion REL - release of task STA - start of task COM - completion of task.
5	A	NO	Statistics type: FIR - first ALL - all BET - between INT - interval NUM - number NO - no statistics.
6	A	СОМ	Time of statistics collection REL - release of task STA - start of task COM - completion of task CLR - clearing of task.
7	I	25	Number of cells for the histogram.
8	R	0.	Upper limit of the 1st cell of the histogram.
9	R	1.	Cell width.

<u>UTC</u> - Specification of User-Defined Task Characteristics

This card is required only if there are user-defined task characteristics for this task. Only one UTC card per task is allowed.

<u>Field</u>	Value	Default	Description
1	A		Card identification (UTC)
2	I		Task number.
3-27	R	0.	The values of the user-defined task characteristics associated with this task.

The value of each user-defined task characteristic is labeled according to the field in which is appears. In other words, the value of user-defined task characteristic I is specified in Field 3, while the value of user-defined task characteristic 25 is specified in Field 27. Up to 25 user-defined task characteristics are allowed for each task.

MOD - Specification of Moderator Function Status

This card is required only if an update in the status of any moderator function is to be made at this task. Only one MOD card per task is allowed.

<u>Field</u>	<u>Value</u>	Default	Description
1	Α		Card identification (MOD).
2	I		Task number.
3	I		Moderator function number for which the status will be updated.
4	A	D	Status of the moderator function specified in Field 3  Deactivate - Deactivate moderator function  Activate - Activate moderator function.
5	A	T	Duration of the status update specified in Field 4  Task - For the task specified in Field 2 only.  Perm - Permanently: until end of simulation or next status update.

Fields 3 - 5 may be repeated so that the status of up to 10 moderator functions may be updated at a single task.

ATA - Specification of Attribute Assignment Information

This card is required only if attribute assignments are to be made at this task. Only one ATA card per task is allowed.

miold.	****	Dof1+	Description
Field	Value	Default	Description
1	A		Card identification (ATA).
2	I		Task number.
3	A	СОМ	Attribute assignment point REL - at task release STA - at task start COM - at task completion.
4	A	IA	<pre>Type of attribute assignment SA - System attribute assignment IA - Information attribute assignment ment RA - Resource attribute assignment.</pre>
5	I	0	Resource number if RA specified in Field 4.
6	I	0	The attribute number to which the assignment is to be made.
7	A	sc	The function to be used in conjunction with the parameter specification (Field 8) in making the assignment. The allowable functions are:  DS Value samples from the distribution set specified as the parameter specification  SC Constant equal to the parameter specification divided by the scale factor (Field 12 of GEN card)  UF User written function (used in conjunction with function USERF(I), where I is the parameter specification).
8	I	0	The parameter specification to be used in making the assignment.

Fields 4 - 8 may be repeated so that up to 6 attribute assignments can be made at a single task.

#### Successor Tasks

A successor task card is required only if branching is to be performed following the completion of this task. Only one successor task card per task is allowed.

# DET - DETERMINISTIC Branching

Field	Value	Default	Description
1	A		Card identification (DET).
2	I		Task number.
3	I	1037 58340	Successor task to task specified in Field 2.

Field 3 may be repeated so that up to 20 successor tasks may be specified.

PRO - PROBABILISTIC Branching

Field	<u>Value</u>	Default	Description
1	A		Card identification (PRO).
2	I		Task number.
3	A	NO	For attribute-based probabilistic branching, the attribute type to be used SA - System attribute.  IA - Information attribute.  RA - Resource attribute.  NO - Not attribute-based probabilistic branching.
4	I	0	Resource number if RA is specified in Field 3.
5	I		Successor task number.
6	R		Probability of selecting the task in Field 5 as the successor to the task in Field 2 (0 < probability < 1). For attribute-based probabilistic branching, the attribute number from which the probability is to be taken.

Fields 5 and 6 may be repeated so that up to 10 successor tasks may be specified. The first branch specified (Fields 5 and 6) is identified as the first branch from the task specified in Field 2.

<u>CFI</u> - CONDITIONAL Branching - Take FIRST branch for which the specified condition is satisfied.

			Aug Ry Latin - abid.
Field	<u>Value</u>	Default	Description
1	A		Card identification (CFI).
2	I		Task number.
3	I		Successor task number.
4	A	NO	Code signifying the type of condition to be met for selecting task in Field 3 as the successor to the task given in Field 2 according to the value specified in Field 5.  TVC-The task specified as value of Field 5 has been completed.  TVN-The task specified as value of Field 5 has not been completed.  TLV-Time of completion of the task in Field 2 is less than or equal to the time specified in Field 5.  TGV-Time of completion of the task in Field 2 is greater than the time specified as value of Field 5.  ALV-The value of the attribute specified in Field 6 is less than or equal to the value specified in Field 5.  AGV-The value of the attribute specified in Field 6 is greater than the value specified in Field 5.  TAC-The task whose number is found in
			the attribute specified in Field 5 has been completed.  TAN-The task whose number is found in
			the attribute specified in Field 5 has not been completed.
			TLA-Time of completion of the task in Field 2 is less than or equal to the time found in the attribute specified in Field 5.
			TGA-Time of completion of the task in Field 2 is greater than the time found in the attribute
			specified in Field 5. ALA-The value found in the attribute
			specified in Field 6 is less than

or equal to the value found in the attribute specified in Field 5.

Field	<u>Value</u>	Default	Description
			AGA-The value found in the attribute specified in Field 6 is greater than the value found in the attribute specified in Field 5.  No -No condition required; task specified in Field 3 is selected as successor (only for last condition specified).
5	R	0.	Value associated with the condition or the attribute which contains the value.
6	Ι	0	Attribute to be used in a comparison of two attribute values. Otherwise, this field should be left blank.
7	Α	IA, if attri- bute required NO, other wise	If attribute values are required for the condition specified in Field 4, the type of attribute to be used SA-System attribute. IA-Information attribute. RA-Resource attribute. NO-No attribute values required.
8	I	0	Resource number if RA specified in Field 7.

Fields 3 - 8 may be repeated so that up to 5 successor tasks may be specified. If a sixth successor is specified, the branch is taken unconditionally.

CAL - CONDITIONAL Branching - Take ALL branches for which the specified condition is satisfied. Input specification is the same as that specified directly above for Conditional Branching - Take First.

## NMO - Network Modifications

Only required if network modifications exist. Only one NMO card per task is allowed.

Field	Value	Default	Description
1	Α		Card identification (NMO).
2	I		Task number.
3	I		The number of the task to be replaced when the task given in Field 2 is completed.
4	I		The number of the task to be in- serted into the network in place of the task specified in preceding field when the task in Field 2 is completed.

Fields 3 and 4 may be repeated so that a total of 10 replacements may be made based on one task completion.

DMO - Distribution Set Modification

Only required if distribution set modifications exist. Only one DMO card per task is allowed.

<u>Field</u>	Value	Default	Description
1	A		Card Identification (DMO).
2	I	71	Task number.
3	I	91 01 019	The distribution set number to be replaced when the task given in Field 2 is completed.
4	I dend of	is belong	The distribution set number to be inserted in place of the distribution set specified in preceding field when the task in Field 2 is completed.

Fields 3 and 4 may be repeated so that a total of 10 replacements may be made based on one task completion.

TCL - Task Clearing

Only required if clearing of tasks is desired. Only one TCL card per task is allowed.

Field	Value	Default	Description
1	Α		Card identification (TCL).
2	os Indo		Task number.
3	I		Task in progress to be halted (cleared) when the task specified in Field 2 is completed.
4		0	Task to be signaled when task in preceding field is cleared. A zero in this field indicates no task to be signaled.

Fields 3 and 4 may be repeated so that a total of 10 tasks may be cleared based on one task completion.

RCL - Resource Clearing

Only required if clearing at resources is desired. Only one RCL card per task is allowed.

<u>Field</u>	Value	Default	Description
1	A		Card identification (RCL).
2	I		Task number.
3	I		Resource to be cleared. If resource is not busy, no clearing is performed.
4	bal Israi	0	Task to be signaled when resource in preceding field is cleared. A zero in this field indicates no task to be signaled.

Fields 3 and 4 may be repeated so that a total of 10 resources may be cleared based on one task completion.

## SWI - Switching Information

This data type is necessary only if switches are to be set as a result of task completion. One card of this type is required for each task causing switching. Only one SWI card per task is allowed.

Field	Value	Default	Description
1	Α		Card identification (SWI).
2	I		Task whose completion will cause the switching action detailed on this card.
3	I		Switch number affected.
4	I	0	Switch value given to switch number in preceding field when task in Field 2 is completed.

Fields 3 and 4 may be repeated so that up to 10 switches may be affected based on one task completion.

## REG - Regulation Information

One card of this type is required for each task causing regulation of state variables. Only one REG card per task is allowed.

<u>Field</u>	<u>Value</u>	Default	Description
1	A		Card identification (REG).
2	I		Task number that regulates, in the prescribed manner, the state variable specified in Field 3.
3	I		Index of SS(•) variable to be regulated upon the completion of the task specified in Field 2.
4	I	0	The index of the SS(*) variable involved in determining the regulation value (if this input is positive). The index of the DD(*) variable involved (if this input is negative). Zero if no SS or DD variable involved.
5	R	1.	Multiplicative constant (CMULT) applied to the variable designated in Field 4 in determining the regulation value.
6	R	0.	A constant value added to the product of the values specified in Fields 4 and 5 in determining the regulation value.
7	A	E.	Indicator specifying how the above determined regulation value will affect the variable designated in Field 2 Increase-Increase by function value. Equal-Regulate to function value. Decrease-Decrease by function value.

Fields 3 - 7 may be repeated so that up to 2 regulations may be made based on one task completion.

## State Variable Monitor Information

Information about a monitor is contained in 1, 2, or 3 data cards. The MON card contains the characteristics of the monitor. One card of this type is required for each monitor. The MTA card is used only if tasks are to be signaled when the specified threshold is reached. The MSW card is used only if switches are to be set when the specified threshold is reached.

MON - Monitor Characteristics

Field	Value	Default	Description
1	A		Card identification (MON).
2	I		Monitor number.
3	A	""	Monitor label (maximum of 8 characters).
4	I The state of	De Desiverpio	<pre>Index of the variable to be monitored &gt; 0 SS(•) variable. = 0 Error. &lt; 0 DD (•) variable.</pre>
5	I	0	<pre>Index of the variable used in com- puting the threshold</pre>
6	R	1.	Multiplicative constant (CMULT) to be used in the threshold function: CADD + CMULT * value of variable in Field 5.
7	R	0.	Additive constant (CADD) to be used in the threshold function: CADD + CMULT * value of variable in Field 5.
8	A	В	Direction of crossing to be observed Positive-Positive direction. Both-Both positive and negative directions. Negative-Negative direction.
9	R	0.	The tolerance within which the crossing is to be detected.

## MTA - Monitor Actuated Task Signaling

This data card is used only if tasks are to be signaled as a result of a threshold crossing. Only one MTA card per monitor is allowed.

Field	Value	Default	Description
1	A		Card identification (MTA).
2	I		Monitor number.
3	I		Task to be signaled when a thres- hold crossing is detected.

Field 3 may be repeated so that up to 10 tasks may be signaled as a result of one threshold crossing.

## MSW - Monitor Actuated Switching

This data card is used only if switches are to be set as a result of a threshold crossing. Only one MSW card per monitor is allowed.

<u>Field</u>	Value	Default	Description
1	A		Card identification (MSW).
2	I		Monitor number.
3	I		Index of the switch to be affected.
4	I of	0	Value to be assumed by the switch specified in Field 3.

Fields 3 and 4 may be repeated so that up to 10 switches may be affected as a result of one threshold crossing.

## <u>SST</u> - State Variable Statistics Information

This card type is required for state variables to be observed for statistical purposes.

<u>Field</u>	Value	Default	Description
1	A		Card identification (SST).
2	I		Statistic number.
3	I	i de de la composición del composición de la composición de la composición del composición de la composición del composición de la composición de la composición del composi	The index of the SS(•) variable to be observed (if positive); the index of the DD(•) variable to be observed (if negative).
4	A	""	Alphanumeric label to be associated with variable identified in Field 2 (maximum of 8 characters).
5	R	0.	The initial value of the variable specified in Field 2.

Fields 2 - 5 may be repeated so that a total of 10 statistics can be specified in a single input record. Additional SST cards may also be used.

### State Variable Plots/Tables

Plot/table information is contained on two types of data cards. The first card (PLO card) contains information on the plot/table. The second card (VAR card) contains information on the variables to be plotted/tabled. One or more VAR cards may be input to describe the variables to be included in the plot/table described by PLO. One PLO card and its associated VAR cards are required for each plot/table.

PLO - State Variable Plot/Table Characteristics

Field	Value	Default	Description
1	A		Card identification (PLO).
2	I		Plot/table number.
3	A	TIME	<pre>Independent axis label (maximum of 8 characters).</pre>
4	I	0	<pre>Storage medium to be used for plot/ table values &gt; 0 Peripheral storage unit number     on which plot/table information     is to be written (required if     multiple plots/tables are     desired). = 0 Plot/table information to be     stored in core (QPSET(·)).     Only 1 plot/table can be requested and Field 2 must be set     to 1 if core is used.</pre>
5	A	P	Plot/table option Quick-Quick plot Plot-Plot only Table-Table only Both-Plot and Table.
6	R	5.	Increment of the independent variable between successive plot points.

<u>VAR</u> - State Variable Plot/Table Variable Information

Field	Value	Default	Description
1	A		Card identification (VAR).
2	I		Plot number (same as Field 2 of associated PLO card).
3	I		Variable number.
4	I		<pre>Index of the variable to be plotted/tabled &gt; 0 SS(·) variable = 0 Error &lt; 0 DD(·) variable</pre>
5	Α .	value in field 3	Plot symbol (maximum of l character).
. 6	A	""	Label associated with the variable being plotted/tabled (maximum of 8 characters).
7	A	M	Key for specifying the lower limit of the scale to be used for the variable specified in Field 4  Minimum-Use minimum value observed during the simulation  Value-Use the value in Field 9  Rounded-Use the largest multiple of the value specified in Field 9 that is less than or equal to the minimum value observed.
8	A	M	Key for specifying the upper limit of the scale to be used for the variable specified in Field 4 Maximum-Use maximum value observed during the simulation  Value-Use the value in Field 10 Rounded-Use the smallest multiple of the value specified in Field 10 that is greater than or equal to the maximum value observed.

<u>Field</u>	<u>Value</u>	Default	Description
9	R	0.	Value associated with the lower limit of the plot ordinate (see Field 7).
10	R	0.	Value associated with the upper limit of the plot ordinate (see Field 8).

Fields 3 - 10 may be repeated so that up to 6 variables may be described on a single data card. Additional VAR cards may also be used to describe additional variables.

### Condensed Data Input Description

A condensed version of the SAINT data input description is presented in Table 6. This table is provided for the user who is already familiar with the detailed description presented previously and desires a brief description of each input field for his continued use.

A brief description of each data input field is provided in Table 6. Abbreviations are used frequently. If a field is required, no default values are shown. However, if an input field is not required, the default value assigned to that field by SAINT is shown in parentheses following the description of the field contents. Some default values are based on the values input in preceding or succeeding fields. For example, if the default value for field 3 is the value input for field 2, the default value for field 3 will be shown as (F2). In addition, some input fields can take one of two default values, depending on the specific situation. Default values of this type are shown as (0/1). An explanation of the conditions under which the default value is selected is provided in the detailed input description.

Many SAINT data cards allow certain fields to be repeated in order to facilitate the preparation of data input. For each data card with this characteristic, the fields that may be repeated are identified. In addition, the maximum number of times that the repeating set of fields may be included on the data card is indicated.

Once again, Table 6 is designed for the SAINT user who is familiar with and has used the detailed input description. Since many abbreviations are employed, care should be taken in using the condensed input description. When in doubt about the contents of a field, the user should refer to the detailed input description for clarification. The page number of the detailed input description for each data type is shown below the card identifier in Field 1.

TABLE 6

CONDENSED SAINT DATA INPUT DESCRIPTION

-	2	e	4	2	9		8	6	10	11	12	13	14	15	16	17	18
GEN	User	Month	Day	Year	Project	Number	Reqd.		Sc Scale	Echo Check?							
(39)	(SAINT)	Θ	8	(2001)	8	Iters.	Comps.		Factor (1.0)	(%)							
	Number	Number	Minimum	Maximum	Commun-	Abs.	Rel.	Error									
SGE	of	of		Step	ication	Error	Error	Option									
(40)	(.)00	SS(.)	(.01*	(Min (F5,		110000	(1)	(4)									
	No. of	No. of	£	No. of	No. of	Network	Distr.	Ranking				-	1			-	
POP	Re-	Res.		System				Rule									
(41)	sonrces	_		Atribs.			to										
	(0)	(0)		(0)													
	Detail	Detail		Resr.				_	S.V.	S.V.	S.V.	5.4.	Resr.	Stat.	First	Sumry	
TUO	Iter.	Iter.		Util.	Tasks	Tasks	Values	Values	Stats.	Stats.	Plots	S	Util.	Task	Iter.	Histo?	
(42)	Start	End	rt	End	Start	End	Start	End	Start	End	Start		Sumry?	Sumry?	Histo?		
	(0)	(F2)	(0)	(F4)	(0)	(F6)	(0)	(F8)	(0)	(F10)	(0)	(F12)	(X)	(Y)	(N)	(N)	
	Distr.	Distr.	Param.	Param.	Param.	Param.											
DIS	Set	Type		2	3	4											
(44)	Number	,000,															
		(00)	(0.)	(0.)	(0.)	(0.)					-			-	-	-	
SIM	Used only Marks end the last.	Used only if multiple netw Marks end of each network the lust.	ultiple ne ach netwoz	k to be	Used only if multiple networks are to be simulated Marks end of each network to be simulated except the last.	except											
FIN	Marks	Marks end of last network	ast networ		to be simulated												
	Theory	100															
-	1361	Stat.				-											
(47)	Stat.	[)	Repeat Fle	telds 2-3	lds 2-3; Maximum = 24	= 24											
	User	Stat.	Initial														
UTI	Stat.	Label	Value	Repeat F	Repeat Fields 2-4; Maximum = 16	Maximum	= 16										
(48)		()	(0.)														
	User	Histo.	er	Upper	Cell												
UHI	Histo.	Label		Lim. of	Width	Repeat F	Repeat Fields 2-6; Maximum = 9	Maximum	6 =								
(49)	Number		s	Cell 1													
		()	(25)	(0.)	(1.)												

-	2	-	4	s	9	7	œ	6	10	11	12	EI	14	15	16	17	18
UPL	User	Indep.	Periph. Storage	Plot Option	Plot Incre-												
(51)	Number	Label (TIME)			ment (5.)												
	User	Var.		Var.	Lower	Upper	Lower	Upper									
NVA (5.3)	Plot	Number		Label	Limit	Limit	Limit	Limit	Repeat F	Repeat Fields 3-9; Maximum = 6	Maximum	9					
1751			(F3)	()	(W)	(M)	(0.)	(0.)									
	Moder.	Initial															
IMO	Func.	Status	Repeat Fi	Repeat Fields 2-3; Maximum = 24	Maximum	= 24											
(54)	Number	(I)															
	Resr.	Resr.	Func.	Param.													
IRA		Atrib.		Spec.	Repeat F	Repeat Fields 3-5; Maximum = 10	. Maximum	= 10									
(55)		Number	(35)	, 0													
	Cuctom	Pinne	Davam	1000		-			-						-		
TSA	Atrib	Type	Spec	Beneat Pi	olde 2-4.	Beneat Fields 2-4. Maximum = 10	01 =										
uct.	Number	-dir	- Jade	webcar to	7 5019	III III III	2										
(99)	1000	(sc)	(0.)														
	Resr.	Resr.															
LRE	Number	Label	Repeat F1	Repeat Fields 2-3; Maximum = 10	Maximum	= 10											
(57)		()															
VSJ	S.V. Number	S.V. Label	Repeat F	Repeat Fields 2-3; Maximum = 10	Maximum	= 10											
(88)		()															
	Task	Task	First	Subs.	Func.	Param.	Resr.	Task	Spec.		Info.	Info.	Task	Resr.	Resr.		
TAS	Number	Label		Rel.	Type	Spec.	Number	Prty.	Task	Pred.?	Choice	Atrib.	Comp.	Rqmt.	Number	Repeat Field 16;	eld 16;
(09)		1	(0/1)	(9999)	(SC)	(0)	(0)	(0.)	Char.	( <u>x</u>	Mech.	Number (0)	Prec.	Code (A)		Maximum = 5	n
	Task	Mark?		Stat.	Collect	Number	Upper	Cell									
STA	Number			Туре	Point	of	Lim. of	Width									
(62)		(N)	(COM)	(NO )	(COM)	(25)	(0.)	(1.)									
	Task	U.T.C.	Repeat Fi	ield 3; Ma	ximum =	25											
(63)	Number	(0.)	Field Nur	Field Number=Characteristic Number+2	acteristi	c Number+	2										
	1	Moder.	1	Duration													
MOD	Number	Func.	Update	Jo	Repeat F.	Repeat Fields 3-5; Maximum = 10	. Maximum	= 10									
(64)		Number	(a)	Status (T)													
		-			-					1		-		-	-	-	

-	2	3		S	9	7	8	6	10	11	12	13	14	15	16	17	18
	Task	Assign.		Resr.	Atrib.	Func.	Param.										
ATA (65)	Number	Point (C)	Type (IA)	Number (0)	Number (0)	Type (6C)	Spec. (0)	Repeat Fi	Repeat Fields 4-8; Maximum =	Maximum =	9 :						
	Task	Succ.															
DET	Number	Task	Repeat F.	ield 3, M	Repeat Field 3; Maximum = 20	20		,				meet.					
(67)			-														
	Task		Resr.	Succ.	Prob.												-
PRO	Number			Task	or	Repeat F	ields 5-6;	Repeat Fields 5-6; Maximum = 10	= 10								
(89)				Number	Atrib.												
	1		1														
		Succ.		Value	Atrib.	Atrib.	Resr.										
CFI	Number			or	Number	Type	Number	Repeat Fi	Repeat Fields 3-8; Maximum =	Maximum =	. 5						
(69)				Atrib.													
				(0.)	(0)	(IA/NO)	(0)										
	Task			Value	Atrib.	Atrib.	Resr.						-				
CAL	Number			or	Number	Type	Number	Repeat Fig	Repeat Fields 3-8; Maximum =	Maximum =	2						
(17)		Number		Atrib.													
				(0.)	(0)	(IA/NO)	(0)										
	Task																
OMN	Number		to	Repeat F	ields 3-4	Repeat Fields 3-4; Maximum = 10	= 10										
(72)			Insert														
	Task	Distr.	Distr.														
DMO	Number			Repeat F	ields 3-4	Repeat Fields 3-4; Maximum = 10	= 10										
(73)			Insert														
	Task		Task														
TCT	Number			Repeat F.	ields 3-4	Repeat Fields 3-4; Maximum = 10	= 10										
(74)			Signal														
	Task		Task														
RCL	Number			Repeat F	ields 3-4	Repeat Fields 3-4; Maximum = 10	= 10										
(72)			Signal														
	Task		New														
SWI	Number				ields 3-4	Repeat Fields 3-4; Maximum = 10	= 10										
(76)			Value														
			(0)														
Jaa	Task	(.) \$8	S.V. in	Mult.	Add.	Effect											
NEC.	Number		Reg.	Const.	Const.	of	Repeat F1	Repeat Fields 3-7; Maximum = 2	Maximum =	. 2							
(77)			Func.			Reg.											
	-		(0)	(1.)	(0.)	(E)											_

18																					
11																					
16																					
15																					
14																					
13																					
12																					
n																					
10																		Jpper	Limit	Value	(0.)
6	Monitor	101.		(0.)								= 10						Lower			(0.)
8	Monitor Monitor	Direct.   Tol.		(B)					= 10			Maximum						Upper	Limit	Key	
1		Const.		(0.)		01			Repeat Fields 3-4, Maximum = 10			Repeat Fields 3-5; Maximum = 10						Lower		Key	
9	Mult.	const.		(1.)		ximum =			elds 3-4			Repeat Fi		Plot	Incre-	ment	(5.)	Var.	Label		()
5			:	(0)		Repeat Field 3; Maximum = 10			Repeat Fi		Initial	Value		Plot	Option		(P)	Plot	Symbol		(F3)
4	S.V.	0	Monitor			Repeat Fi		New	Switch	Value (0)	Stat.	Label		Periph.	Storage	Unit	(0)	s.v.	to	Plot	
3	or	Label		()	Task	to	Signal	Switch	Aver	Change	$\overline{}$	to	Collect			Label			Number		
2	Monitor	Number			Monitor	Number		Monitor	Number		s.v.	Stat.	Number		Plot	Number			Plot	Number	
1	1000	NON	(67)			MTA	(80)		MSM	(81)		SST	(82)		PLO	(83)			VAR	(84)	

#### SECTION IV

## SAINT USER-WRITTEN SUBPROGRAMS

SAINT includes nine user-written subprograms that are used to define additional model components. These subprograms and the functions they can perform are shown in Table 7. By including the appropriate SAINT COMMON blocks, all SAINT COMMON variables are available to the user. In addition, the user has access to the user support subprograms that are described in Section V.

#### SAINT USER-WRITTEN SUBPROGRAMS

Subprograms
-------------

#### Function

Subroutine ENDIT (NITER)

Prepares user-generated iteration summary report for iteration NITER and initializes user-generated statistical storage arrays. Automatically called by SAINT at the end of iteration NITER.

Subroutine INTLC

Defines the initial values of the state variable vector SS(·) and the switch vector IS(·). Automatically called by SAINT at the end of state variable data input processing.

Subroutine MODRF (MFN, NNODE)

Computes and causes the effect of moderator function MFN on the performance of task NNODE. The effect can alter TTIME, the baseline task performance, or PFIRB, the probability of taking the first branch specified upon completion of the task. Automatically called by SAINT if moderator function MFN is active when the performance of NNODE is being scheduled.

Function PRIOR(ITASK)

Computes the priority PRIOR of task ITASK prior to the assignment of resources. Automatically called by SAINT immediately preceding the assignment of resources to tasks that have been released.

Subroutine STATE

Contains algebraic, difference, and differential equations which define the state variables of the model. Automatically called by SAINT when the values of state variables are to be updated.

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Subprograms

Function

Subroutine UERR (KODE)

Prepares user-generated error report when a SAINT execution error occurs. Automatically called by SAINT when execution error KODE is detected.

Subroutine UINPT

Reads user-generated input data. Automatically called by SAINT following the processing of all SAINT input data.

Function USERF (JJ)

Determines the value of USERF when the user-written function (UF) is specified on input. The value of JJ is the parameter specification associated with the function.

Subroutine UOTPT

Prepares user-generated simulation summary report for usergenerated statistics and other user-defined quantities. Automatically called by SAINT at the end of all required iterations.

#### SECTION V

#### SAINT USER SUPPORT SUBPROGRAMS

With the advent of SAINT user-written subprograms, the SAINT user may require direct access to SAINT variables. Since SAINT maintains lists and pointer systems, a number of subprograms are provided to facilitate the retrieval of variable values. These user-callable support subprograms allow the user to access frequently required SAINT variables as well as to collect statistics on any user-defined variables. They are organized by function in the following six tables, where their descriptions and argument definitions are given.

Table Number	Function
8	Attribute Values
9	User-Defined Task Characteristics
10	Task Scheduling
11	Random Deviate Generators
12	User-Generated Statistics
13	Simulation Status

# SAINT USER SUPPORT SUBPROGRAMS: ATTRIBUTE VALUES

Subprogram		Function
	GETIA (NAT, VALUE)	Retrieves VALUE as the value of information attribute NAT of the information packet associated with the task now being processed.
Subroutine	PUTIA (NAT, VALUE)	Sets information attribute NAT of the information packet associated with the task now being processed to the value of VALUE.
Subroutine	GETRA (NRE, NAT, VALUE)	Retrieves VALUE as the value of resource attribute NAT of resource NRE.
Subroutine	PUTRA (NRE, NAT, VALUE)	Sets resource attribute NAT of resource NRE to the value of VALUE.
Subroutine	GETSA (NAT, VALUE)	Retrieves VALUE as the value of system attribute NAT.
Subroutine	PUTSA (NAT, VALUE)	Sets system attribute NAT to the value of VALUE.

# SAINT USER SUPPORT SUBPROGRAMS: USER-DEFINED TASK CHARACTERISTICS

Subprogram	Function
Subroutine GETTC (NNODE,NCHAR,VALUE)	Retrieves VALUE as the value of user-defined task characteristic NCHAR of task NNODE.
Subroutine PUTTC (NNODE,NCHAR,VALUE)	Sets User-defined task characteristic NCHAR of task NNODE to the value of VALUE.

# SAINT USER SUPPORT SUBPROGRAMS: TASK SCHEDULING

Subprogram	Function
Subroutine GETPR(ITASK, VALUE)	Retrieves VALUE as the value of the task priority of task ITASK.
Subroutine PUTPR(ITASK, VALUE)	Sets the task priority of task ITASK to the value of VALUE.
Subroutine QRANK(IRANK)	Changes the ranking procedure used in ranking those tasks awaiting the assignment of resources to IRANK, where IRANK is 1 (low value first based on priority), 2 (high value first based on priority), 3 (FIFO), or 4 (LIFO).
Function TIMEQ(IDUM)	Retrieves the time that the task now being processed has been residing in the file of tasks awaiting the assignment of resources. This function is only accessible from function PRIOR. The argument IDUM is a dummy argument required by ANSI FORTRAN.
Function TMARK(IDUM)	Retrieves the mark time contained in the information packet associated with the task now being processed.  The argument IDUM is a dummy argument required by ANSI

FORTRAN.

# SAINT USER SUPPORT SUBPROGRAMS: RANDOM DEVIATE GENERATORS

Subprogram	Function
Function BETA(J)	Generates a random deviate from a Beta or Beta-Pert distribution with parameters in distribution set J.
Function DRAND(IY)	Generates a uniform random number DRAND over the interval (0,1) using the computer system's random number routine. This function is machine specific. The argument IY is the initial random number seed (ISEED).
Function ERLNG(J)	Generates a random deviate from an Erlang distribution with parameters in distribution set J.
Function GAMM(J)	Generates a random deviate from a Gamma distribution with parameters in distribution set J.
Subroutine NPOSN(J,NPSSN)	Generates a random deviate NPSSN from a Poisson distribution with parameters in distribution set J.
Function RLOGN(J)	Generates a random deviate from a log-normal distribution with parameters in distribution set J.
Function RNORM(J)	Generates a random deviate from a normal distribution with parameters in distribution set J.
Function TRNGL(J)	Generates a deviate from a triangular distribution with parameters in distribution set J.
Function UNFRM(J)	Generates a random deviate from a uniform distribution with parameters in distribution set J.
Function WEIBL(J)	Generates a random deviate from a Weibull distribution with parameters in distribution set J.

## SAINT USER SUPPORT SUBPROGRAMS: USER-GENERATED STATISTICS

Sub	pr	og	ram	
	_			

#### Function

Subroutine CLEAR

Initializes all statistical storage arrays for user-generated statistics. Automatically called by SAINT following the processing of all input data cards.

Subroutine CLRHI (IND)

Initializes the statistical storage arrays associated with the collection of user-generated histograms. If IND is equal to 0, statistical storage for all histgrams is initialized; if IND is greater than 0, statistical storage for the histogram identified by IND is initialized.

Subroutine CLROB(IND)

Initializes the statistical storage arrays associated with the collection of user-generated statistics for variables based on observation. If IND is equal to 0, statistical storage for all variables based on observation is initialized; if IND is greater than 0, statistical storage for the variable identified by IND is initialized.

Subroutine CLRPT(IND)

Initializes storage arrays and peripheral storage units associated with the preparation of user-generated plots. If IND is equal to 0, storage for all user-generated plots is initialized; if IND is greater than 0, storage for the plot identified by IND is initialized.

#### Subprogram

#### Function

Subroutine CLRTP(IND)

Initializes the statistical storage arrays associated with the collection of user-generated statistics for time-persistent variables. If IND is equal to 0, statistical storage for all time-persistent variables is initialized; if IND is greater than 0, statistical storage for the variable identified by IND is initialized.

Subroutine UCLCT(XX,ICLCT)

If ICLCT is greater than 0, records value XX as an observation on variable ICLCT. If ICLCT equals 0, computes and reports statistics on all variables based on observation. If ICLCT is less than 0, computes and reports statistics on variable -ICLCT.

Subroutine UHIST(XX,IHIST)

If IHIST is greater than 0, determines the cell number associated with the value XX for histogram IHIST and increases the cell content by 1. If IHIST equals 0, prints and plots all user-generated histograms. If IHIST is less than 0, prints and plots user-generated histogram -IHIST.

Subroutine UPLOT(XX,T,IPLOT)

If IPLOT is greater than 0, IPLOT is the plot number and UPLOT stores values of the dependent variables XX (up to ten values per plot) for a value of the independent variable T. If IPLOT equals 0, prints table and/or plot for all user-generated plots. If IPLOT is less than 0, prints table and/or plot for user-generated plot -IPLOT.

### Subprogram

#### Function

Subroutine UTMSA(XX,T,ISTAT)

Integrates variable ISTAT assuming that the value during the past interval is the average of XX and the value XX at the last cell to UTMSA for variable ISTAT. Computation and reporting for variable ISTAT is performed by subroutine UTMST.

Subroutine UTMST(XX,T,ISTAT)

If ISTAT is greater than 0, integrates variable ISTAT assuming that the value during the interval up to time T is the value of XX at the last call to UTMST for variable ISTAT. XX is the value that variable ISTAT will have during the next interval. If ISTAT equals 0, computes and reports statistics on all user-generated time-persistent variables. If ISTAT is less than 0, computes and reports statistics on usergenerated time-persistent variable -ISTAT.

# SAINT USER SUPPORT SUBPROGRAMS: SIMULATION STATUS

Subprogram	Function
Subroutine DMPAR	Prints the current status of all tasks awaiting the assignment of resources.
Subroutine DMPMF	Prints the current status of all moderator functions.
Subroutine DMPRS	Prints the current status of all resources.
Subroutine DMPSA	Prints the current status of all system attributes.
Subroutine DMPST	Prints the current status of all tasks now being performed.
Subroutine DMPSV	Prints the current status of all state variables.

### SECTION VI

### SAINT INPUT ERRORS

Two separate and self-contained input processors are available for use with the SAINT simulation program. The first processor performs maximum error checking. This processor outputs primary error specifications following the individual card images on the echo check, and secondary error specifications following the complete card image echo check. When a SAINT input error occurs, the error will be identified by a printed error message describing the error and its location.

The second input processor performs no error checking. It should be used only when the SAINT user is certain that no errors appear when using the maximum error checking input processor.

With these capabilities, the user will be able to initially check his input data using the maximum error checking processor and then make subsequent runs with the same data deck using the no error checking processor in order to save computer time. For both input processors, all undefined input variables, except those required by SAINT, will be given default values.

### SECTION VII

### SAINT EXECUTION ERRORS

The SAINT simulation program is designed to monitor its own execution and detect any errors that arise. When an error is detected, execution is automatically terminated by calculating the square root of a negative number, so that subprogram traceback information will be printed. SAINT then provides complete information detailing the status of the system at the point in time when the error occurs. This information includes the error code number, the time that the error occurred, the iteration being processed, as well as the current status of all tasks, resources, attributes, moderator functions, and state variables.

When a SAINT execution error occurs, the error will be identified by an error code number. Table 14 provides the description, probable cause, and location associated with each error code. The information included in Table 14 along with the status report printed when the error occurs should provide sufficient information to locate and correct the error.

Following the printing of the error report, SAINT automatically calls subroutine UERR(KODE). This subroutine is user-written and may be used to generate user-required error reports on the status of user-defined variables. The argument KODE is set equal to the code number of the error detected.

TABLE 14

SAINT EXECUTION ERROR DESCRIPTIONS

Error Code	Error Condition	Location of Call to SERR	
3001	Failed integration accuracy test; user specified execution abort. Probable cause: specified accuracy requirements are too strict.	UPDATE	144
3002	Failed accuracy test in locating thres- hold crossing; user specified execution abort. Probable cause: specified accu- racy requirements are too strict.	UPDATE	189
3003	Sum of the branching probabilities for a task that requires probabilistic branching does not equal 1.0. Probable cause: incorrect assignment of branching probabilities during execution.	GASP	372
3004	One of the branching probabilities for a task that requires probabilistic branching is less than 0. Probable cause: incorrect assignment of branching probability during execution.	GASP	369
3005	All available storage for information attribute packets has been allocated. Probable cause: associated array dimensions are too small (see Table 16, No. 13, for arrays affected).	GASP	478
3006	All available storage for tasks being performed and tasks awaiting assignment of resources has been allocated. Probabl	FILEM e	11
	cause: associated array dimensions are too small (see Table 16, No. 1, for arrays affected).		
3007	Value of the variable TTIME (task performance time) is less than 0. Probable cause: incorrect specification of varia-	SCHAT	67
	ble value in user-written subprogram.		

Error Code	Error Condition	Locatio Call to	
3008	Value of the variable PFIRB (probability of selecting the first branch for a task that requires probabilistic branching) is less than 0. Probable cause: incorrect specification of variable value in user-written subprogram.	SCHAT	74
3009	Value of the variable PFIRB (probability of selecting the first branch for a task that requires probabilistic branching) is greater than 1. Probable cause: incorrect specification of variable value in user-written subprogram.	SCHAT	75
3010	Not all sink tasks required for completion of simulation have been performed. However, no other tasks are being performed. Probable cause: incorrect branching specifications (incorrect network formulation).	RMOVE	14
3101	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	BETA	7
3102	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	ВЕТА	4
3103	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	BETA	5
3104	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	ERLNG	8

Error Code	Error Condition	Location of Call to SERR
3105	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	ERLNG 5
3106	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	ERLNG 6
3107	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	GAMM 7
3108	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	GAMM 4
3109	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	GAMM 5
3110	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	NPOSN 9
3111	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	NPOSN 6

Error Code	Error Condition	Location of Call to SER	
3112	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	NPOSN	7
3113	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	RLOGN	7
3114	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	RLOGN	4
3115	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	RLOGN	5
3116	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	RNORM	8
3117	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	RNORM	5
3118	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	RNORM	6

Error Code	Error Condition	Location Call to	
3119	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	TRNGL	8
3120	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	TRNGL	6
3121	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	TRNGL	7
3122	Distribution set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: incorrect specification of argument in calling subprogram.	UNFRM	8
3123	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	UNFRM	5
3124	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UNFRM	6
3125	Distribution Set number specified as an argument to this subprogram refers to a distribution set that contains an illegal distribution type for this subprogram. Probable cause: Incorrect specification of argument in calling subprogram.	WEIBL	8

Error Code	Error Condition	Location o	
3126	Distribution set number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	WEIBL	5
3127	Distribution set number specified as an argument to this subprogram is greater than the largest distribution set number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	WEIBL	6
3201	Histogram number specified as an argument to this subprogram is less than 0. Probable cause: incorrect specification of argument in calling subprogram.	CLRHI	5
3202	Histogram number specified as an argument to this subprogram is greater than the largest histogram number specified on input. Probable cause: incorrect specification of argument in calling subprogram	CLRHI	6
3203	Statistic number specified as an argument to this subprogram is less than 0. Probable cause: incorrect specification of argument in calling subprogram.	CLROB	5
3204	Statistic number specified as an argument to this subprogram is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram.		6
3205	Plot number specified as an argument to this subprogram is less than 0. Probable cause: incorrect specification of argument in calling subprogram.	CLRPT	5
3206	Plot number specified as an argument to this subprogram is greater than the largest plot number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	CLRPT	6
3207	Statistic number specified as an argument to this subprogram is less than 0. Probable cause: incorrect specification of argument in calling subprogram.	CLRTP	6

Error Code	Error Condition	Location Call to	
3208	Statistic number specified as an argument to this subprogram is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram		7
3209	Clearing of user-generated histograms is requested. However, no user-generated histograms are defined. Probable cause: call made to inappropriate clearing subprogram from a user-written subprogram.	CLRHI	4
3210	Clearing of user-generated statistics based on observation is requested. However, no user-generated statistics based on observation are defined. Probable cause: call made to inappropriate clearing subprogram from a user-written subprogram.	CLROB	4
3211	Clearing of user-generated statistics for time persistent variables is requested. However, no user-generated statistics for time persistent variables are defined. Probable cause: call made to inappropriate clearing subprogram from a user-written subprogram.	CLRTP	5
3212	Clearing of user-generated plots is requested. However, no user-generated plots are defined. Probable cause: call made to inappropriate clearing subprogram from a user-written subprogram.	CLRPT	4
3301	Statistic number specified as an argument to this subprogram for output purposes is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UCLCT	9
3302	Statistic number specified as an argument to this subprogram is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UCLCT	16

Error Code	Error Condition	Location Call to	
3303	Histogram number specified as an argument to this subprogram for output purposes is greater than the largest histogram number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UHIST	10
3304	Histogram number specified as an argument to this subprogram is greater than the largest histogram number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UHIST	20
3305	Statistic number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	UTMSA	6
3306	Statistic number specified as an argument to this subprogram is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UTMSA	7
3307	Value of the independent variable specified as an argument to this subprogram is not greater than or equal to the last specified value of the independent variable. Probable cause: incorrect specification of argument in calling subprogram	UTMSA	11
3308	Statistic number specified as an argument to this subprogram for output purposes is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UTMST	9
3309	Statistic number specified as an argument to this subprogram is greater than the largest statistic number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UTMST	16

Error Code	Error Condition	Location Call to	
3310	Value of the independent variable specified as an argument to this subprogram is not greater than or equal to the last specified value of the independent variable. Probable cause: incorrect specification of argument in calling subprogram.	UTMST	18
3311	Plot number specified as an argument to this subprogram for output purposes is greater than the largest plot number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UPLOT	29
3312	Plot number specified as an argument to this subprogram is greater than the largest plot number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	UPLOT	11
3313	Value of the independent variable specified as an argument to this subprogram is not monotonic. Probable cause: incorrect specification of argument in calling subprogram.		132
3314	Collection or reporting of user-generated histograms is requested. However, no user-generated histograms are defined. Probable cause: call made to inappropriate subprogram from a user-written subprogram.		7
3315	Collection or reporting of user-generated statistics based on observation is requested. However, no user-generated statistic based on observation are defined. Probablicause: call made to inappropriate subprogram from a user-written subprogram.	- cs le	6
3316	Collection or reporting of user-generated statistics for time persistent variables is requested. However, no user-generated statistics for time persistent variables are defined. Probable cause: call made to inappropriate subprogram from a user-written subprogram.	UTMSA	5

Error Code	Error Condition	Locatio Call to	
3317	Collection or reporting of user-generated statistics for time persistent variables is requested. However, no user-generated statistics for time persistent variables are defined. Probable cause: call made to inappropriate subprogram from a user-written subprogram.		6
3318	Collection or reporting of user-genera- ted plots is requested. However, no user-generated plots are defined. Prob- able cause: call made to inappropriate subprogram from a user-written subprogram	UPLOT	9
3319	The number of variables for the plot specified as an argument to this subprogram is 0. Collection for this plot has been requested. Probable cause: incorrect specification of argument in calling subprogram.	UPLOT	14
3320	The number of variables for the plot specified as an argument to this subprogram is 0. Reporting for this plot has been requested. Probable cause: incorrect specification of argument in calling subprogram.	UPLOT	30
3401	Attribute number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	GETIA	5
3402	Attribute number specified as an argument to this subprogram is greater than the largest attribute number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	GETIA	6
3403	Task number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	GETPR	4
3404	Task number specified as an argument to this subprogram is greater than the largest task number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	GETPR	5

Error Code	Error Condition	Location Call to	
3405	Attribute number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification in calling subprogram.	GETRA	5
3406	Attribute number specified as an argument to this subprogram is greater than the largest attribute number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	GETRA	6
3407	Resource number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification in argument in calling subprogram	GETRA	7
3408	Resource number specified as an argument to this subprogram is greater than the largest resource number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	GETRA	8
3409	Attribute number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram		4
3410	Attribute number specified as an argument to this subprogram is greater than the largest attribute number specified on input. Probable cause: incorrect specification of argument in calling subprogram		5
3411	Characteristic number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	GETTC	7
3412	Characteristic number specified as an argument to this subprogram is not defined for the task specified as an argument. Probable cause: incorrect specification	GETTC i	8
	of argument in calling subprogram.		

Error Code	Error Condition	Location of Call to Si	
3413	Task number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect speci- fication of argument in calling subprogram	GETTC	5
3414	Task number specified as an argument to this subprogram is greater than the largest task number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	GETTC	6
3501	Attribute number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram		5
3502	Attribute number specified as an argument to this subprogram is greater than the largest attribute number specified on input. Probable cause: incorrect specification of argument in calling subprogram	PUTIA	6
3503	Task number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram	PUTPR	4
3504	Task number specified as an argument to this subprogram is greater than the larg- est task number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	PUTPR	5
3505	Attribute number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification in calling subprogram.	PUTRA	7
3506	Attribute number specified as an argument to this subprogram is greater than the largest attribute number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	PUTRA	8
3507	Resource number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	PUTRA	5

Error Code	Error Condition	Location Call to	
3508	Resource number specified as an argument to this subprogram is greater than the largest resource number specified on input. Probable cause: incorrect specification of argument in calling subprogram	PUTRA	6
3509	Attribute number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	PUTSA	4
3510	Attribute number specified as an argument to this subprogram is greater than the largest attribute number specified on input. Probable cause: incorrect specification of argument in calling subprogram	PUTSA	5
3511	Characteristic number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram.	PUTTC	7
3512	Characteristic number specified as an argument to this subprogram is not defined for the task specified as an argument. Probable cause: incorrect specification of argument in calling subprogram	PUTTC	8
3513 .	Task number specified as an argument to this subprogram is less than or equal to 0. Probable cause: incorrect specification of argument in calling subprogram	PUTTC	5
3514	Task number specified as an argument to this subprogram is greater than the largest task number specified on input. Probable cause: incorrect specification of argument in calling subprogram.	PUTTC	6
3515	Ranking rule specified as an argument to this subprogram is not equal to 1, 2, 3, or 4. Probable cause: incorrect speci- fication of argument in calling subprogram		5
3601	Report on the status of moderator functions is requested. However, no moderator functions are defined. Probable cause: call made to inappropriate status reporting subprogram from a user-written subprogram.		10

Error Code	Error Condition	Location of Call to SERE	
3602	Report on status of resources is requested. However, no resources are defined. Probable cause: call made to inappropriations tatus reporting subprogram from a userwritten subprogram.		1
3603	Report on status of system attributes is requested. However, no system attributes are defined. Probable cause: call made to inappropriate status reporting subprogram from a user-written subprogram.	DMPSA 10	)
3604	Report on status of state variables is requested. However, no state variables are defined. Probable cause: call made to inappropriate status reporting subprogram from a user-written subprogram.	DMPSV 8	3

### SECTION VIII

### SAINT OPERATING PROCEDURES

SAINT is written in ANSI standard FORTRAN IV and can be run on any machine that has a FORTRAN compiler. In this and subsequent sections, general information relative to the operation of the SAINT program is provided.

SAINT normally utilizes four input and output devices. The variable NCRDR is set to the input device number. variable NPRNT is set to the output device number. The variable NRNIT is set to a peripheral device number to be used during input processing and initialization prior to each iteration. Output to this device is formatted. The variable NRENT is set to a peripheral device number to be used during the reinitialization of program variables at the end of each iteration. The values of these variables are specified in the main program. In the version of SAINT documented herein and available for distribution, these variables are defined as NCRDR=5, NPRNT=6, NRNIT=8, and NRENT=9. The variable NPUNCH is also defined in the main program for the convenience of the user in generating punched card output. It is defined as NPUNCH=7. In addition, SAINT utilizes peripheral devices in the preparation of state variable and user-generated plots. The device numbers to be used are specified by the user on SAINT data cards. The devices should be made available through the use of proper JCL for the user's machine.

In SAINT, function DRAND is the only machine-specific subprogram. Function DRAND is used by SAINT to generate a pseudo-random number in the interval (0,1). It is suggested that the coding of function DRAND be replaced by the random number generator in use at your computer center.

### SECTION IX

### SAINT OVERLAY STRUCTURE

The basic philosophy employed in the design of SAINT was that additions, modifications, and deletions are to be expected. Because of this, the SAINT computer program was designed in a modular form to facilitate adaptation. This same design philosophy allows efficient use of core storage by providing the means to develop a storage-saving overlay structure.

In designing the SAINT overlay structure, the SAINT subprograms were divided into four groups. The first group of subprograms remains in core storage throughout the simulation process. The other three groups are brought into core storage one at a time, dependent upon the status of the simulation being performed. Table 15 shows the manner in which the SAINT subprograms were divided into groups.

Group 1 remains in core storage throughout the program's execution, as the subprograms contained within Group 1 are accessed from more than one of the remaining three subprogram groups. When the main program calls subroutine DATIN to begin processing the SAINT data cards, group 2 is brought into core storage along with group 1.

After processing all data cards, subroutine DATIN returns control to the main program. The main program then calls subroutine GASP, causing group 2 to be removed from core storage and group 3 to be brought in. Group 3 contains all subprograms necessary to perform the simulation.

When all iterations have been completed, subroutine GASP returns control to the main program. The main program then calls subroutine SUMRY for the purpose of preparing the required output reports. This causes group 3 to be removed from core storage and group 4 to be inserted.

Following the completion of the summary reports, subroutine SUMRY returns control to the main program. If no
additional SAINT networks are to be simulated, execution
is terminated. However, if additional networks are to be
analyzed, the entire simulation process is restarted with a
call to DATIN from the main program.

TABLE 15

GROUPINGS OF SAINT SUBPROGRAMS

Group 1	Grou	p 2	Grou	p 3	Group 4
ASSGN BETA CLEAR CLEAR CLRHI CLROB CLRPT CLRTP DMPAR DMPFL DMPMF DMPSS DMPSS DMPSV DRAND ERLNG GAM GAMM HISTO INTLC NPOSN PRNTH PRNTS RLOGN RNORM SERR STATE TRNGL UCLCT UERR UHIST UNFRM UPLOT USERF UTMSA UTMST WEIBL	ATASS BETAXF BUILD CNCVT CONDIT CVT DATIN DET DFAUS DFAUT DISTR DMODS DSWT ECHO ECHOS ERRIN GEN GTCHAR IMODFN INIT INITS IRATT ISATT MAP MODFN MONIT LLABL	LPACK MSWT MTASK NMOD OUTPT PERTXF PLOTS PNABA POP PROB RCLEAR REG SGEN STAT TASK TCLEAR UCOLL UHSTO UINPT UPLTS UTIME UVAR VAR	ATSET COLST ENDIT FILEM GASP GETIA GETPR GETRA GETSA GETTC MODRF NFIND PRIOR PUTIA PUTPR PUTRA PUTSA PUTTC	QRANK RMOVE RPLOT SCHAT SCHED SCOND SSAVE TIMEQ TMARK UPDATE	SUMRY UOTPT

### SECTION X

### DIMENSION REQUIREMENTS FOR SAINT ARRAYS

The version of the SAINT simulation program documented herein and available for distribution has been designed to accommodate a model with the characteristics listed in Table 16.

The model characteristics that the SAINT program will accept can be altered by changing the values of the variables given in column 3 of Table 16 to the desired values in the main program and by changing the dimensions of the arrays affected (column 5) in the main program and all SAINT subprograms where their associated COMMON block appears. The main program for SAINT is shown in Figure 7. A general description of the characteristic associated with each COMMON block appears in Table 17. The COMMON blocks included in each SAINT subprogram are shown in Table 18. The definitions of all SAINT COMMON variables are provided in Documentation for the SAINT Simulation Program (2).

For example, assume that a SAINT model requires that the largest task number be 500. Entry 3 of Table 16 provides the information for altering the largest task number. The name of the variable that is set to the largest task number is IMN (presently set to 100). Thus, the first step in the alteration process is to remove the following statement from the main program:

IMN = 100

and replace it with the statement:

IMN = 500.

Once this has been accomplished, the next step in the alteration process involves changing the dimensions of the arrays affected, as shown in column 5, from 100 to 500. Thus, all dimensioned arrays which appear in the COMMON block COM10 must be altered. The arrays included in COM10 are shown in the main program (Figure 7). The new version of COM10, where all arrays are dimensioned to 500, will replace the old version in the main program. In addition, Table 18 indicates that COM10 must also be replaced in 32 SAINT subprograms.

As soon as the alterations described above have been completed, the SAINT program will accept models whose largest task number is 500. The same alteration procedure is to be followed in order to change any of the other model characteristics.

TABLE 16

# DIMENSION REQUIREMENTS FOR SAINT ARRAYS

	a company of the first the contract of the contract of			Labeled COMMON	
8	Controlling Characteristic M	Current Maximum Value	Variable Name for Maximum Value	Arrays Affected	Arrays Affected
1 -	<ol> <li>Number of tasks being performed + number of tasks awaiting assignment of resources.</li> </ol>	100	a	COM02	NSET(ID*4), QSET(ID*3)
2	2. Largest distribution set number.	100	MPARM	COM09	All dimensioned arrays in COM09
ë	3. Largest task number.	100	IMN	COM10	All dimensioned arrays in COM10
4	4. Largest resource number.	20	MOPNO	COM11	BUSY, LLRES, NBUS, NOPTR, TLST, RSTAT (MOPNO*4)
ů,	. Number of tasks that require resources + total number of task-resource associations specified.	009	MNOPA	COM11	NOPA
ý					
	* 2) + (total number of conditional branches specified * 5).	850	муава	COM12	УАВА
7	7. Number of tasks that cause task modifications + (total number of tasks modifications specified * 2) + number of tasks that cause distribution set modifications specified * 2) + number of distribution set modifications specified * 2) + number of tasks that cause task clearing + (total number of tasks clearings specified * 2) + number of tasks clearings specified * 2) + number of tasks that cause resource clearing + (total number of tasks that resource clearing * 2) + number of tasks that require different predecessors + total number	os.			
	of predecessors to tasks that require different predecessors.	250	IMNA	COM12	NABA

8	Controlling Characteristic	Current Maximum Value	Variable Name for Maximum Value	Labeled COMMON Block Containing Arrays Affected	Arrays Affected
<b>6</b>	Number of user-defined task characteristics for all tasks (the number of user-defined task characteristics for a task is equal to the larcest characteristic number defined for that task).	200	MTCHR	COM12	STCHR
6	Largest moderator function number.	20	MMDFN	COM13	MDFNS, MFSTW
10	<ol> <li>Number of tasks at which moderator function status is updated + (total number of moderator function status updates specified</li> <li>2).</li> </ol>	300	WESTU	COM13	WESTU
п	11. Number of statistics tasks.	20	HXSTA	COM14	NSINK, KSTPE, KSTTM, XSTUS, NCELS, XLOW, WIDTH, SUMAI, SUMAF
12	12. (Number of statistics tasks * 2) + total number of cells specified for statistics task histograms.	1350	HINCLS	COM14	JCELS
13	<ol> <li>Number of information packets in the network * (number of attributes per packet + 1).</li> </ol>	1000	HAXDS	COM15	DESCR
7	14. Largest resource number ** number of resource attributes per resource.	100	HDOAT	COM15	DOATT
15	15. (Number of tasks at which attribute assignments are to be made * 2) + (total number of attribute assignments to be made * 4).	008	MDSTR	COM15	NDSTR
16	16. Largest system attribute number.	100	MSYAT	COM15	SYSAT
11	<ol> <li>Largest index for state variable equations (SS(·) or DO(·) variables).</li> </ol>	100	MEQT	COM17	All dimensioned arrays in COM17 <sup>1</sup>
18	18. Largest switch number.	20	MNSWA	COM18	IS

δl	Controlling Characteristic	Current Maximum Value	Variable Name for Maximum Value	Labeled COMMON Block Containing Arrays Affected	Arrays Affected
21	<ol> <li>Number of tasks at which switch values are changed + (total number of specified switch value changes as a result of task completion</li> <li>2).</li> </ol>	300	МВАБ	CONTB	NABAD
×	20. Number of tasks at which state variable values are regulated + (total number of specified state variable regulations as a result of task cumpletion * 5).	009	MDDR	COMIB	YABAR
23	21. Largest state variable monitor number.	20	MFLAG	COM19	LFLAG, NPOSS, NPOST, LLMON, THRES (MFLAG*6)
22	22. Number of state variable monitors causing tasks to be signaled + total number of specified task signalings as a result of monitor action.	9	T-dNOW	COM19	NABAT
2	2). Number of state variable monitors causing switch values to be changed + (total number of specified switch value changes as a result of monitor action # 2)	Ş	SHOP	Olino	
24	24. Number of state variables for which statistics are to be collected.	50 20	MSTAT	COM20	MARAS All dimensioned arrays in COM20
25	25. Largest state variable plot number.	10	MPLOT	COM21	DTPLT, IITAP, NNPTS, NNVAR, NNVP, NVP (MPLOT*NNVPP)
26	<ol> <li>Largest number of variables plotted on any state variable plot.</li> </ol>	10	MNVPP	COM21	LLPHI, LLPLO, LLSYM, PPHI, PPLO, NVP (HPLOT" MNVPP), LLSYP (MNVPP + 1,2)
27	27. Number of state variable core plot point sets * (number of variables being plotted + 1).	1100	МФД	COM21	QPSET

8	Controlling Characteristic	Current Maximum Value	Variable Name for Maximum Value	Labeled COMMON Block Containing Arrays Affected	Arrays Affected
8	28. Largest statistic number for user-generated statistics based on observation.	50	MNCLT	COM23	LLUGC, USOBV
Ŕ	<ol> <li>Largest statistic number for user-generated statistics based on time-persistent variables.</li> </ol>	50	MNSTP	COM23	LLUGT, TTCLR, USTPV
30.	30. Largest user-generated histogram number.	20	MNHIS	COM23	LLUGH, NNCEL, HHLOM, HHMID
Ä	31. (Number of user-generated histograms * 2) + total number of cells specified for user-generated histograms.	540	MNCEL	COM23	JOCEL
32.	32. Largest user-generated plot number.	10	MNPLT	COM24	DPLOT, ITAPE, NPTSV, NVARS
33.	33. Largest number of variables plotted on any user-generated plot.	10	MNVAR	COM24	LPHIH, LPLOW, LSYMB, PHIH, PLOM, LLLUGP (MNVAR+1, 2)
ž .	34. Number of user-generated core plot point sets * (number of variables being plotted + 1)	1100	MNCUP	COM24	UPSET

The following arrays appear in a DIMENSION statement in subroutine UPDATE: SI,DI,A1,A2,A3,A4,A5,A6,A7 The dimensions of these arrays must be changed in accordance with any changes made to the maximum number of state variables allowed.

```
CCMMON /COMO1/ ID, IM, IMM, IMM, MMN, MAXDS, MDAD, MODR, MONPT, MONSS.
                 MOCAT, MOOP, MOSTR, MEGT, MFLAG, MMFTS, MMOFN, MMSTU,
                 MNCEL, MNCLS, MNCLT, MNCUP, MNHIS, MNOPA, MNPLT, MNPTO.
                 MNSTP, MNSHA, MNVAR, MNVPP, MOPNO, MPARM, MPLOT, MSTAT,
                 MSYAT, MTCHR, MXSTA, MYABA, NOO
COMMON /COMO2/ ATRIB(3), JTRIB(2), QSET(3CO), NSET(4CC), MFA, MXX,
                 MFE(3), MLE(3), NQ(3)
COMMON /COMO3/ IPGS, JPOS, KPOS, LPOS, MPOS, NPA, NAN, IERRH, IERRF, IFIN,
                 IIECH, INDXS, INDXT, INDX, JNDX, KNOX, IP, NUMFL, ICONT,
                 IISED, HIVAL, IBLNK, IZERO, LA, LB, LC, LD, LE, LF, LG, LH, LI,
                 LJ,LK,LL,LM, LN,LO,LP,LQ,LR,LS,LT,LU,LV,LW,LX,LY,LZ
CCMMON /COM04/ IDFAL(4), KREAD(40), IFLAG(50), IRSUL(50), RESUL(50),
                 IAEC(8,50), KARD(90), IDIG(9)
CCMMON /COMOS/ NPROJ, MON, NOAY, NYR, NAME (2), NRUN, NRUNS, NSKSR,
                 NSKST, LLCVO, NNEQD, NNEQS, NNEQT
CCMMON /COMOS/ TNCW, TTNEX, MFAD, SEED, I SEED, NCROR, NPRNT, NPUNCH,
                 NRNIT, NRENT, MNDC, NCC, NDTN, NNTC
CCMMON /COMOT/ NDE, NOPAT, NSYAT, NOOP, NNM, NNPA, NMOFN, NN, NPRMS, IFL PR,
                 JFLPR, KRNK, XINN, AFLAG, NNCLT, NNHIS, NNPLT, NNSTA,
                 NNSTP, NPLOT, NSTTS
COMMON /COMOS/ NEIP, NEIS, NSIP, NSIS, ITRACE, JTRACE, NRTSP, NRTEP,
                 KTRACE, MTRACE, IIPSR, IISSR, IGRAF, JGRAF, IJTRAC,
                 NSVVS, NSVVE, NTSOE, NTSOS, LTRACE, NRTSS, NRTES
COMMON /COM39/ PARAM(103,5), NPTBU(100), PARM1(100), PARM4(100)
COMMON /COMIC/ CACIN(100,3),ITCHR(100),LLTSK(100,2),LSINK(100),
                 MACIN(133, 4), MFEN(180), MFSTT(188), NFTBU(188),
                 MOP(160), MPO(100), NOCH(100,2), NOEL(100), NOPT(100),
                 NPAR(100), NPO(130), NPOOR(103), NPODS(100), NPOP(100),
                 NPCR(100), NPSGN(100), NREL (100), NRELP(100),
                 NREL2(100), NSIGN(100), NTC(100), NTCHR(100),
                 NTYPE (103) , KMARK(100) , XMARK(100)
COMMON /COM11/ BUSY(20), LLRES(20, 2), NBUS(20), NOPTR(20), TLST(20),
                 NOPA (600), RSTAT (80)
COMMON /COM12/ YABA(850), NABA(250), STCHR(200)
COMMON /COM13/ MDFNS(20), MFSTW(20), MFSTW(300)
CCMMON /COM14/ NSINK (50), KSTPE (50), KSTTM (50), XSTUS (50), NCELS (50),
                 XLCW(50), WIDTH(50), SUMAI (50,5), SUMAF (50,5),
                 JCELS (1350)
COMMON /COM15/ DESCR(1333), DOATT (100), NOSTR(800), SYSAT(100)
COMMON /COM16/ AAERR, DTMAX, DTMIN, DTSAV, IITES, LLERR, RRERR, TTLAS,
                 TTSAV, OTSUG, DTFUL, DTNOW, ISEES, RESLS, OTACC, LLSAV,
                 LSAVE
CCMMON /COM17/ SS(100),SSL(100),DD(100),DDL(100),LLSVR(100,2)
CCMMON /COM18/ IS(20),NABAD(300),YABAR(600)
CCHMON /COM19/ LFLAG(20), NPOSS(20), NPOST(20), LL MON(20,2),
                 NAEAT (40), NABAS (60), THRES (120)
COMMON /COM20/ NSTAI (20), LLSVS (20,2), SSTPV (20,6)
COMMON /COM21/ DTPLT(10). IITAP(10), NNPTS(10), NNVAR(10), NNVP(10)
                 LLPLT, NNPT, LLPHI(10), LLPLO(10), LLSYM(10), PPHI(10),
                 PPLO(13), NVP(103), LLSVP(11,2), GPSET(1100)
COMMON /COM22/ TTIME, PFIRS
CCMMON /COM23/ LLUGC(20,2),USOBV(20,5),LLUGT(20,2),TTCLR(20),
                 USTPV (20,6), LLUGH (20,2), NNCEL (20), HHLOW (20),
                 HHWID (20) , JJCEL (546)
CCHMON /COM24/ OPLOT(10), ITAPE(10), NPTSV(13), NVARS(10), LPLOT,
                 NPTEX, LPHIH(10), LPLOW(10), LSYME(10), PHIH(10),
                 PLOW(13), LLUGP(11, 2), UPSET(1100)
```

Figure 7(1). Main Program for SAINT.

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```
C++++*INITIALIZE READ, PRINT, AND PUNCH KEYS
C
       NCRDR=5
       NFRNT=5
       NPUNCH=7
       NENIT=8
       NRENT=9
C
C+**** DEFINE VARIABLES WHICH REPRESENT ARRAY MAXIMA AND SIMULATION C*****LIMITS
C
       ID=100
       I MN = 1 60
       IFNA= 250
       MAX CS=1000
       MCAD=300
       MDDR=600
       MONPT=40
       MDNSS=60
       MOOAT=160
       MOOP=1100
       MOSTR=860
       MEGT=100
       MFLAG=20
       MMOFN=20
       MMSTU=300
       MNCEL =540
       MNCLS=1350
       MNCLT=20
       MNCUP=1100
       MNH IS=20
       MNOPA=600
       MNPLT=10
       MNSTP=20
       CS = AW ZAM
       MNVAR=10
       MNVPP=10
       MCPN0=23
       MPARM=100
       MFL OT = 10
       MSTAT=20
       MSYAT=100
       MTCHR=200
       MXSTA=50
       MYABA=950
C
C++++ EXECUTION CYCLE -- READ INPUT DATA, THEN INITIATE THE SIMULATION
      IFIN=0
  100 CALL DATIN
IF(IERRF.EQ.0) CALL GASP
IF(IERRF.EQ.0) CALL SUMRY
IF (IFIN.EQ.0) GO TO 130
       STOP
C
       END
```

Figure 7(2). Main Program for SAINT.

# TABLE 17 SAINT COMMON BLOCK CHARACTERISTICS

COMMON Block	Characteristics
COM01	Maximum Array Dimensions
COM02	Filing System
COM03	Input Processing I
COM04	Input Processing II
COM05	General Information
COM06	Simulation Control
COM07	Program Options
COM08	Output Options
COM09	Distribution Sets
COM10	Tasks I
COM11	Resources
COM12	Tasks II
COM13	Moderator Functions I
COM14	Statistics Tasks
COM15	Attributes
COM16	State Variable Updating
COM17	State Variables
COM18	Switching and Regulation
COM19	State Variable Monitors
COM20	State Variable Statistics
COM21	State Variable Plots
COM22	Moderator Functions II
COM23	User-Generated Statistics
COM24	User-Generated Plots
	129

TABLE 18

COMMON BLOCKS INCLUDED IN SAINT SUBPROGRAMS

Subprogram							COMMON		Block	ck	Number	ber												
	01	02	03	04	02	90	07	80	60	10	11	12	13	14	15	16	17	18	19	20	21 2	22	23	24
Main Program	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×
ASSGN		×				×			×	×	×				×							×		
ATASS	×		×	×			×		×	×					×									
ATSET		×								×	×				×							×		
BETA							×		×															
BETAXF									×															
BUILD			×	×																				
CLEAR							×																	
CLRHI							×																×	
CLROB							×																×	
CLPRT							×																	×
CLRTP						×	×																×	
CNCVT			×	×																				
COLST					×	×	×	×						×	×									
CONDIT	×		×	×			×			×		×												
CAT			×	×																				
DATIN	×		×	×	×	×	×																	
DET	×		×	×						×		×												
DFAUS	×		×	×	×		×									×	×	×	×	×	×			
DFAUT	×		×	×	×	×	×	×	×	×	×	×	×	×	×								×	×
DISTR	×			×			×		×															
DMODS	×		×	×			×		×	×														
DMPAR		×			×	×																		
DMPFL	×	×				×	×			×					×									
DMPMF					×	×	×						×											
DMPRS					×	×	×				×				×									
DMPSA					×	×	×								×									
DMPST		×			×	×																		
DMPSV					×																			

On hand or an and		-	1	1	1	1	0	THOMASON	1.	01001	M	Minho	1									1	1	1
Name	01	02	03	04	05	90		08	101	100	11	12	13	14	15	16	17	18 1	19 2	20 21	1 22	23	24	4
DSWT	×		×	×						×								×						
ЕСНО	×		×	×	×	×	×	×	×	×	×	×	×	×	×							×		×
ECHOS	×		×	×	×		×			×						×	×	×	×	×	×			
ERLING							×		×															
ERRIN			×			×																		
FILEM	×	×				×	×			×														
GAM						×																		
GAMM							×		×															
GASP	×	×			×		×	×	×	×	×	×	×	×	×	×	×	×	×	×	×			
GEN	×		×	×	×	×																		
GETIA		×					×								×									
GETPR							×			×														
GETRA							×				×				×									
GETSA							×								×									
GETTC							×			×		×												
GTCHAR	×		×	×						×		×												
HISTO						×	×							×										
IMODEN	×		×	×			×						×											
INIT	×	×	×			×	×			×	×	×		×								×		
INITS	×				×		×	×		×						×	×		×	×				
IRATT	×		×	×			×		×		×				×						^			
ISATT	×		×	×			×		×						×						×			
LLABL	×		×	×	×		×				×						×							
LPACK				×		×																		
MAP			×	×																				
MODEN	×		×	×			×			×			×											
MONIT	×		×	×	×	×	×												×					
MSWI	×		×	×															×					
MTASK	×		×	×															×					
NFIND		×																						
NMOD	×		×	×		×	×		×	×														
OUTPT	×		×	×				×																
PERTAF									×															

Cubarogram		1				1	COMMON	1	Plank	1.	Minhor	,										1
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UVAR	×		×	×																	×
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WEIBL						×	×		×												

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